Bearingless encoders

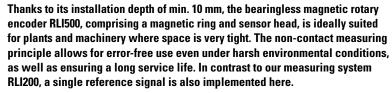


Incremental, large hollow shaft reference signal, magnetic

RLI500 (hollow shaft)

Push-pull / RS422





IP68 / IP69k protection, special encapsulation technology and tested resistance to cyclic humidity and damp heat offer the highest levels of reliability, even in exposed outdoor use.

This bearingless encoder can be mounted on shafts with a diameter up to max. 350 mm.









High rotational speed

High protection level

on Shock/vi

Reverse polarity

Hard-wearing and robust

- · High shock and vibration resistance.
- Sturdy housing with IP67 protection. Option: special housing for maximum resistance against condensation (IP68 / IP69k, resistance to cyclic humidity acc. to EN 60068-3-38 as well as damp heat acc. to EN 60068-3-78).
- Non-contact measuring system, free from wear, ensures a long service life.

Fast start-up

- · Function display via LED.
- Large mounting tolerance between magnetic band and sensor head.
- · Requires very little installation space.
- · Slotted hole fixing ensures simple alignment.

Order code RLI500

$\begin{bmatrix} 8.\mathsf{RLI500} \\ \mathsf{Type} \end{bmatrix} \cdot \begin{bmatrix} \mathsf{X} \ \mathsf{X} \\ \bullet \ \bullet \end{bmatrix} 1 \begin{bmatrix} \mathsf{X} \ \mathsf{X} \\ \bullet \ \bullet \end{bmatrix} \cdot \begin{bmatrix} \mathsf{XXXXXX} \\ \bullet \end{bmatrix} \cdot \begin{bmatrix} \mathsf{0700} \\ \bullet \end{bmatrix}$

- a Magnetic ring mounting method
- 1 = Press fit 1)
- 2 = Hub screw
- 3 = Screwed flange 1)
- Model
- 1 = IP67, standard
- 2 = IP68 / IP69k and humidity tested acc. to EN 60068-3-38, EN 60068-3-78
- Output circuit / Supply voltage
- 1 = RS422 / 4.8 ... 26 V DC
- 2 = Push-pull / 4.8 ... 30 V DC

- d Type of connection
- 1 = radial cable, 2 m [6.56'] PUR
- A = radial cable, special length PUR *)
- *) Available special lengths ²⁾ (connection type A): 3, 5, 8, 10, 15, 20 m [9.84, 16.40, 26.25, 32.80, 49.21, 65.62'] order code expansion .XXXX = length in dm ex.: 8.RLI500.2112A.04096.0700.0030 (for cable length 3 m)
- Pulses per revolution 2048, 3200, 4096, 6400 (for hollow shaft ø 70 mm) (e.g.: 2048 pulses => 02048)

• Hollow shaft diameter 0700 = 70 mm [2.76"] 3)

Optional on request

- other pulse rates
- other hollow shaft diameter (up to max. 350 mm)

Press fit



Hub screw



Screwed flange



- 1) On reques
- 2) Cable lengths >10 m only possible with supply voltage >10 V.
- 3) With magnetic ring mounting method 1 or 3 on request.



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Accessories / Displays Order no. - Counter, tachometer, time counter and position display in one device Codix 560, preset counter 6.560.010.XXX - Scalable display 6-digit - Readable via RS232/485 interface or configurable via MODBUS or CR/LF protocol 571T touch, multifunction preset counters - Measuring function for RPM, speed, speed from elapsed time, machine cycle 6.571T.01X.XXX time, throughput time (reciprocal rotary speed), as well as numerous count 8-digit functions such as position display - Fast counting input (250 kHz/HTL, 1 MHz/RS422) - 4 switching outputs as limit values (response time < 1 ms) - Scalable analog output (response time < 150 ms), resolution 16 bit - Serial interface RS232 or RS485 for reading in and out the data

Further Kübler accessories can be found at: kuebler.com/accessories Further Kübler cables and connectors can be found at: kuebler.com/connection-technology

Technical data

Mechanical characteristi	cs	
Maximum speed		12000 min ⁻¹
Protection	model 1 model 2	IP67 acc. to EN 60529 IP68 / IP69k acc. to EN 60529, DIN 40050-9 and humidity tested
		acc. to EN 60068-3-38, EN 60068-3-78
Working temperature		-20 °C +80 °C [-4 °F +176 °F]
Shock resistance		5000 m/s ² , 1 ms
Vibration resistance		300 m/s ² , 10 2000 Hz
Pole gap		5 mm from pole to pole
Housing (sensor head)		aluminum
Cable		2 m [6.56'] , PUR 8 x 0.14 mm ² [AWG 26], shielded, may be used in trailing cable installations
Status LED	green red	pulse index error; speed too high or magnetic fields too weak

Electrical charac	teristics	;					
Output circuit		RS422		Pus	Push-pull		
Supply voltage		4.8 2	4.8 26 V DC		4.8 30 V DC		
Power consumption (no load)		typ. 25 mA max. 60 mA		,,	typ. 25 mA max. 60 mA		
Permissible load/channel		120 oh	120 ohm		+/- 20 mA		
Min. pulse edge interval		1 µs	1 μs		1 μs		
Signal level	HIGH LOW	min. 2.5 V max. 0.5 V			+V - 2.0 V . 0.5 V		
Reference signal		1 x per revolution					
System accuracy		typ. 0.3° with s		aft tolerar	nce g6		
Pulse rate [ppr] 1) max. speed min-1		2048 7300	3200 4600	4096 3600	6400 2300		

Approvals

CE compliant in accordance with

EMC Directive 2014/30/EU **RoHS Directive** 2011/65/EU

Terminal assignment

Output circuit	Type of connection	Cable (isolate unused cores individually before initial start-up)									
1.2	1, 2 1, A	Signal:	0 V	+V	Α	Ā	В	B	0	ō	Ť
1, 2		Core color:	WH	BN	GN	YE	GY	PK	BU	RD	shield ²⁾

+V: Supply voltage encoder +V DC

0 V: Supply voltage encoder ground GND (0 V)

A, $\overline{\mathsf{A}}$: Incremental output channel A Incremental output channel B

B, \overline{B} : 0, $\overline{0}$: Reference signal

Plug connector housing (shield)

www.kuebler.com

¹⁾ With an input frequency of the evaluation unit of 250 kHz.

²⁾ Shield is attached to connector housing.



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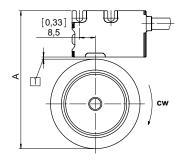
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Mounting orientation and permissible mounting tolerances

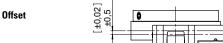
Distances

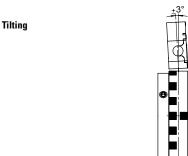


T Distance sensor head / magnetic ring: 0.1 ... 1.5 [0.004 ... 0.06] (1 [0.04] recommended)

Torsion







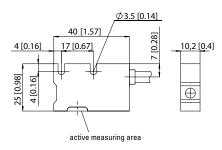
Impulsions par tour	Α
	for distance sensor head / magnetic ring = 1 mm [0.04]
2048, 3200, 4096, 6400	128.0 [5.04]

Warning: When mounting the sensor head, please ensure its correct orientation to the magnetic ring!

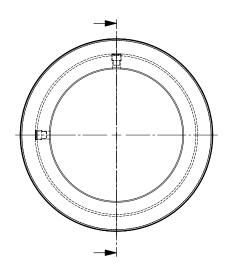
Dimensions

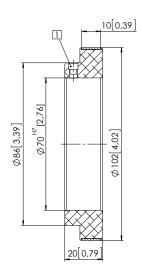
Dimensions in mm [inch]

Sensor head



Magnetic ring (hub screw) pulse rate 2048. 3200, 4096, 6400





1 M5 set screw