

Absolute encoders – multiturn

Compact, robust electronic multiturn, magnetic	Sendix M3663R (shaft)	SSI
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The Sendix M36 with Energy Harvesting Technology is an electronic multiturn encoder in miniature format, without gear and without battery.

The "R"obust version is particularly suitable for use in harsh environments. Protected up to IP69k, resistance against shock and extreme temperature fluctuations, the Sendix M36 encoder is suitable even for demanding outdoor applications.



Safety-Lockplus™	Standard option stainless steel 1.4404	Standard option seawater resistant	High rotational speed	Temperature range -40°... +85°C	High protection level IP	High shaft load capacity	Shock / vibration resistant	Reverse polarity protection	Energy Harvesting

Highest robustness

- Sturdy bearing construction in Safety-Lockplus™ design for particularly high resistance.
- Extra large bearings.
- Mechanically protected shaft seal.
- Protection level IP66, IP67 and IP69k in one device.
- Wide temperature range -40°C ... +85°C.
- Without gear and without battery, thanks to the Energy Harvesting technology.

Application oriented

- Angular measurement deviation ±0,5°.
- Repeat accuracy ±0.2°.
- Short control cycles, clock frequency with SSI up to 2 MHz.
- Max. resolution 38 bit (14 bit ST + 24 bit MT).

Order code	8.M3663R.XX2X.XXX2								
Shaft version	Type	a	b	c	d	e	f	g	h
a Version				c Interface / supply voltage					f Resolution (singleturn)
1 = standard ¹⁾ clamping flange ø 42 mm [1.65"]				2 = SSI / 10 ... 30 V DC					A = 10 bit ST 2 = 12 bit ST 3 = 13 bit ST 4 = 14 bit ST
7 = stainless steel V4A ²⁾ clamping flange ø 42 mm [1.65"] all metal parts accessible from outside are out of stainless steel V4A				d Type of connection					g Resolution (multiturn)
				2 = radial cable, 1 m [3.28'] PUR B = radial cable, special length PUR *) 4 = radial M12 connector, 8-pin					2 = 12 bit MT 6 = 16 bit MT A = 20 bit MT 4 = 24 bit MT
b Shaft (ø x L), with flat				*) Available special lengths (connection type B): 2, 3, 5, 8, 10, 15 m [5.56, 9.84, 16.40, 26.25, 32.80, 49.21'] order code expansion .XXXX = length in dm ex.: 8.M3663R.132B.G322.0030 (for cable length 3 m)					<i>Optional on request</i> - Ex 2/22 (only for connection type 4) - other shaft diameters out of V4A stainless steel
1 = ø 6 x 12.5 mm [0.24 x 0.49"] 3 = ø 8 x 15 mm [0.32 x 0.59"] 5 = ø 10 x 20 mm [0.39 x 0.79"] 2 = ø 1/4" x 12.5 mm [0.49"] E = ø 10 x 20 mm [0.39 x 0.79"], stainless steel V4A				e Code					
				B = SSI, binary G = SSI, gray					

1) Not in conjunction with shaft type "E".
2) Only in conjunction with shaft type "E" + type of connection "4".

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Mounting accessory for shaft encoders			Order no.
Coupling	Bellows coupling ø 19 mm [0.75"] for shaft 8 mm [0.32"]		8.0000.1102.0808 ¹⁾
Cables and connectors			Order no.
Preassembled cables	M12 female connector with coupling nut, 8-pin, A coded, straight single ended 2 m [6.56'] PUR cable		05.00.6051.8211.002M ¹⁾
Connectors	M12 female connector with coupling nut, 8-pin, A coded, straight (metal)		05.CMB 8181-0 ¹⁾
	M12 female connector with coupling nut, 8-pin, A coded, straight (stainless steel V4A)		8.0000.5136.0000.V4A

Further Kübler accessories can be found at: kuebler.com/accessories

Further Kübler cables and connectors can be found at: kuebler.com/connection-technology

1) Not for version "7" (V4A stainless steel)

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Technical data

Mechanical characteristics			
Maximum speed	4000 min ⁻¹ 2000 min ⁻¹ (continuous)		
Starting torque at 20°C [68°F]	< 0.01 Nm		
Shaft load capacity	radial	80 N	
	axial	40 N	
Weight	approx. 250 g [8.82 oz]		
Protection acc. to EN 60529/DIN 40050-9	IP66, IP67, IP69k		
Working temperature range	-40°C ... +85°C [-40°F ... +185°F]		
Materials	version "1" (standard)	version "7" (stainless steel)	
	shaft	V2A	V4A
	flange	aluminum	V4A
	housing	zinc die-cast	V4A
	cable	PUR	–
Shock resistance acc. to EN 60068-2-27	5000 m/s ² , 4 ms		
Vibration resistance acc. to EN 60068-2-6	300 m/s ² , 10 ... 2000 Hz		

Electrical characteristics	
Supply voltage	10 ... 30 V DC
Current consumption (no load)	max. 30 mA
Reverse polarity protection of the supply voltage	yes
Short-circuit proof outputs	yes ¹⁾

SSI interface		
Output driver	RS485 transceiver type	
Permissible load / channel	max. +/- 30 mA	
Signal level	HIGH	typ 3.8 V
	LOW with I _{Load} = 20 mA	typ 1.3 V
Resolution singleturn	10 ... 14 bit	
Angular measurement deviation ²⁾	±0,5°	
Repeat accuracy	±0.2°	
Number of revolutions (multiturn)	max. 24 bit	
Code	binary or gray	
SSI clock rate	50 kHz ... 2 MHz	
Data refresh rate	2 ms	
Monoflop time	≤ 15 µs	
Note: If the clock cycle starts within the monoflop time a second data transfer begins with the same data. If the clock cycle starts after the monoflop time the cycle begins with the new values. The update rate is dependent on the clock speed, data length and monoflop time.		

SET input		
Input	active HIGH	
Input type	comparator	
Signal level (+V = supply voltage)	HIGH	min. 60 % of +V, max: +V
	LOW	max. 30 % of +V
Input current	< 0.5 mA	
Min. pulse duration (SET)	10 ms	
Input delay	1 ms	
New position data readable after	1 ms	
Internal processing time	200 ms	
<p>The encoder can be set to zero at any position by means of a HIGH signal on the SET input. Other preset values can be factory-programmed. The SET input has a signal processing time of approx. 1 ms, after which the new position data can be read via SSI. Once the SET function has been triggered, the encoder requires an internal processing time of typ. 200 ms; during this time the supply voltage must not be switched off. The SET function should be carried out whilst the encoder is at rest.</p> <p>If this input is not used, it should be connected to 0 V (Encoder ground GND) in order to avoid interferences.</p>		

DIR input	
<p>Direction input: A HIGH signal switches the direction of rotation from the default cw to ccw. This inverted function can also be factory-programmed.</p> <p>If this input is not used, it should be connected to 0 V (Encoder ground GND) in order to avoid interferences.</p>	
Response time (DIR input)	1 ms

Power-ON	
<p>After Power-ON the device requires a time of approx. 150 ms before valid data can be read.</p> <p>Hot plugging of the encoder should be avoided.</p>	

Approvals	
UL compliant in accordance with	File no. E224618
CE compliant in accordance with	
EMC Directive	2014/30/EU
RoHS Directive	2011/65/EU
ATEX Directive	2014/34/EU (for Ex 2/22 variants)
UKCA compliant in accordance with	
EMC Regulations	S.I. 2016/1091
RoHS Regulations	S.I. 2012/3032
UKEX Regulations	S.I. 2016/1107 (for Ex 2/22 variants)

1) Short circuit proof to 0 V or to output when supply voltage correctly applied.
 2) Over the whole temperature range.

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electronic multiturn, magnetic**

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Terminal assignment

Interface	Type of connection	Features	Cable (isolate unused cores individually before initial start-up)									
2	2, B	SET, DIR	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	⊥
			Core color:	WH	BN	GN	YE	GY	PK	BU	RD	shield

Interface	Type of connection	Features	M12 connector, 8-pin									
2	4	SET, DIR	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	⊥
			Pin:	1	2	3	4	5	6	7	8	PH

+V: Supply voltage encoder +V DC
 0 V: Supply voltage encoder ground GND (0 V)
 C+, C-: Clock signal
 D+, D-: Data signal
 SET: Set input
 DIR: Direction input
 PH ⊥: Plug connector housing (shield)

Top view of mating side, male contact base



M12 connector, 8-pin

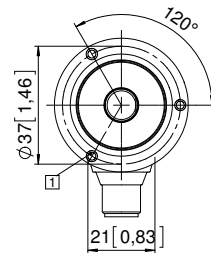
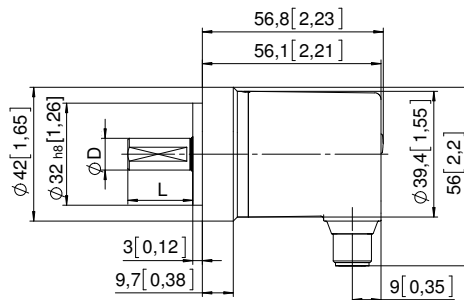
Dimensions

Dimensions in mm [inch]

**Aluminum,
clamping flange, ø 42 [1.65]
version 1**

□ 3 x M3, 6 [0.24] deep

D	Fit	L
6 [0.24]	h7	12.5 [0.49]
8 [0.32]	h7	15 [0.59]
10 [0.39]	f7	20 [0.79]
1/4"	h7	12.5 [0.49]



**Stainless steel V4A
clamping flange, ø 42 [1.65]
version 7**

□ 4 x M4, 8 [0.31] deep

D	Fit	L
10 [0.39]	f7	20 [0.79]

