

Compact electronic multiturn, magnetic

Sendix M3663 / M3683 (shaft / hollow shaft)

SSI



The Sendix M36 with Energy Harvesting Technology is an electronic multiturn encoder in miniature format, without gear and without battery. With a size of just 36 x 53 mm it offers a blind hollow shaft of up to 10 mm.

















capacity









protection salt spray tested

Reliable and insensitive

- Sturdy bearing construction in Safety-Lock™ design for resistance against vibration and installation errors.
- · Reduced number of components ensures magnetic insensitivity.
- IP67 protection and wide temperature range -40 °C ... +85 °C.
- · Without gear and without battery, thanks to the Energy Harvesting technology.

Application oriented

- Angular measurement deviation ±0,5°.
- Repeat accuracy ±0.2°.
- Short control cycles, clock frequency with SSI up to 2 MHz.
- Max. resolution 38 bit (14 bit ST + 24 bit MT).

Order code **Shaft version**

|X|X|2|X|. |X|X|X|28.M3663 0000 000

- a Flange
- 1 = clamping flange, IP67, ø 36 mm [1.42"]
- 3 = clamping flange, IP65, ø 36 mm [1.42"]
- 2 = synchro flange, IP67, ø 36 mm [1.42"]
- 4 = synchro flange, IP65, ø 36 mm [1.42"]
- **b** Shaft (ø x L), with flat
- $1 = \emptyset 6 \times 12.5 \text{ mm} [0.24 \times 0.49"]$
- $3 = \emptyset 8 \times 15 \text{ mm} [0.32 \times 0.59"]$
- $5 = \emptyset 10 \times 20 \text{ mm} [0.39 \times 0.79"]$
- $2 = \emptyset 1/4" \times 12.5 \text{ mm} [0.49"]$
- Interface / supply voltage 2 = SSI / 10 ... 30 V DC

- Type of connection
- 1 = axial cable, 1 m [3.28'] PUR
- A = axial cable, special length PUR *)
- 2 = radial cable, 1 m [3.28'] PUR
- B = radial cable, special length PUR *)
- 3 = axial M12 connector, 8-pin
- 4 = radial M12 connector, 8-pin
- *) Available special lengths (connection types A, B): 2, 3, 5, 8, 10, 15 m [5.56, 9.84, 16.40, 26.25, 32.80, 49.21'] order code expansion .XXXX = length in dm ex.: 8.M3663.432A.G322.0030 (for cable length 3 m)
- Code
- B = SSI, binary
- G = SSI, gray

- Resolution (singleturn)
- A = 10 bit ST
- 2 = 12 bit ST
- 3 = 13 bit ST 4 = 14 bit ST
- Resolution (multiturn)
- 2 = 12 bit MT
- 6 = 16 bit MT
- A = 20 bit MT
- 4 = 24 bit MT

Optional on request

- Ex 2/22 (only for connection types 3 and 4)
- surface protection salt spray tested



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Order code	8.M3683 .	. XX2X .	XXXX2
Hollow shaft	Туре	0000	000

a Flange

2 = with stator coupling, IP65, ø 46 mm [1.81"]

3 = with spring element, long, IP65

5 = with stator coupling, IP67, ø 46 mm [1.81"]

6 = with spring element, long, IP67

b Blind hollow shaft

(insertion depth max. 18.5 mm [0.73"])

1 = Ø 6 mm [0.24"]

 $3 = \emptyset 8 \text{ mm } [0.32"]$

4 = ø 10 mm [0.39"]

 $2 = \emptyset 1/4''$

• Interface / supply voltage

2 = SSI / 10 ... 30 V DC

1 Type of connection

1 = axial cable, 1 m [3.28'] PUR

A = axial cable, special length PUR *)

2 = radial cable, 1 m [3.28'] PUR

B = radial cable, special length PUR *)

3 = axial M12 connector, 8-pin

4 = radial M12 connector, 8-pin

*) Available special lengths (connection types A, B): 2, 3, 5, 8, 10, 15 m [5.56, 9.84, 16.40, 26.25, 32.80, 49.21'] order code expansion .XXXX = length in dm ex.: 8.M3683.242A.G322.0030 (for cable length 3 m)

Code

B = SSI, binary

G = SSI, gray

• Resolution (singleturn)

A = 10 bit ST

2 = 12 bit ST

3 = 13 bit ST

4 = 14 bit ST

Resolution (multiturn)

2 = 12 bit MT

6 = 16 bit MT

A = 20 bit MT

4 = 24 bit MT

Optional on request

- Ex 2/22 (only for connection types 3 and 4)

- surface protection salt spray tested

Mounting accessory for sha	ft encoders	Order no.
Coupling	8.0000.1102.0808	
Mounting accessory for holl	ow shaft encoders Dimensions in mm [inch]	Order no.
Torque pin, ø 4 mm	with fixing thread	8.0010.4700.0000
for flange with spring element (flange type 3 + 6)	8[0,31] 5[0,2] SW7 [0,28] 9 30[1,18]	
Cables and connectors		Order no.
Preassembled cables	M12 female connector with coupling nut, 8-pin, A coded, straight open ended 2 m [6.56'] PUR cable	05.00.6051.8211.002M
Connectors	M12 female connector with coupling nut, 8-pin, A coded, straight (metal)	05.CMB 8181-0

Further Kübler accessories can be found at: <u>kuebler.com/accessories</u>

Further Kübler cables and connectors can be found at: kuebler.com/connection-technology



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Technical data

Mechanische Kennwerte	
Maximum speed shaft or blind hollow shaft version without shaft seal (IP65)	6000 min ⁻¹ 3000 min ⁻¹ (continuous)
shaft or blind hollow shaft version with shaft seal (IP67)	4000 min ⁻¹ 2000 min ⁻¹ (continuous)
Starting torque at 20 °C [68 °F]	
without shaft sea	< 0.007 Nm
with shaft seal (IP6)	< 0.01 Nm
Shaft load capacity radia	40 N
axia	00 N
axia	20 N
Weight	ca. approx. 210 g [7.41 oz] g
u///u	
Weight	ca. approx. 210 g [7.41 oz] g
Weight Protection acc. to EN 60529	ca. approx. 210 g [7.41 oz] g IP65 or IP67 -40 °C +85 °C [-40 °F +185 °F]
Weight Protection acc. to EN 60529 Working temperature range	ca. approx. 210 g [7.41 oz] g IP65 or IP67 -40 °C +85 °C [-40 °F +185 °F] stainless steel
Weight Protection acc. to EN 60529 Working temperature range Materials shaft / hollow shaf	ca. approx. 210 g [7.41 oz] g IP65 or IP67 -40 °C +85 °C [-40 °F +185 °F] stainless steel aluminum
Weight Protection acc. to EN 60529 Working temperature range Materials shaft / hollow shaft flanger	ca. approx. 210 g [7.41 oz] g IP65 or IP67 -40 °C +85 °C [-40 °F +185 °F] stainless steel aluminum zinc die-cast
Weight Protection acc. to EN 60529 Working temperature range Materials shaft / hollow shaf flange housing	ca. approx. 210 g [7.41 oz] g IP65 or IP67 -40 °C +85 °C [-40 °F +185 °F] stainless steel aluminum zinc die-cast PUR

Electrical characteristics	
Supply voltage	10 30 V DC
Current consumption (no load)	max. 40 mA
Reverse polarity protection of the supply voltage	yes
Short-circuit proof outputs	yes 1)

SSI interface	
Output driver	RS485 transceiver type
Permissible load / channel	max. +/- 30 mA
Signal level HIGH	typ 3.8 V
LOW with I _{Load} = 20 mA	typ 1.3 V
Resolution singleturn	10 14 bit
Angular measurement deviation 2)	±0,5°
Repeat accuracy	±0.2°
Number of revolutions (multiturn)	max. 24 bit
Code	binary or gray
SSI clock rate	50 kHz 2 MHz
Data refresh rate	2 ms
Monoflop time	≤ 15 µs

Note: If the clock cycle starts within the monoflop time a second data transfer begins with the same data. If the clock cycle starts after the monoflop time the cycle begins with the new values. The update rate is dependent on the clock speed, data length and monoflop time.

SET input		
Input		active HIGH
Input type		comparator
Signal level (+V = supply voltage)	HIGH LOW	min. 60 % of +V, max: +V max. 30 % of +V
Input current		< 0.5 mA
Min. pulse duration (SET)		10 ms
Input delay		1 ms
New position data readable after		1 ms
Internal processing time		200 ms

The encoder can be set to zero at any position by means of a HIGH signal on the SET input. Other preset values can be factory-programmed. The SET input has a signal processing time of approx. 1 ms, after which the new position data can be read via SSI. Once the SET function has been triggered, the encoder requires an internal processing time of typ. 200 ms; during this time the supply voltage must not be switched off.

The SET function should be carried out whilst the encoder is at rest.

The number of preset value writing cycles is limited to 10,000.

If this input is not used, it should be connected to 0 V (Encoder ground GND) in order to avoid interferences.

DIR input

Direction input: A HIGH signal switches the direction of rotation from the default cw to ccw. This inverted function can also be factory-programmed.

If this input is not used, it should be connected to 0 V (Encoder ground GND) in order to avoid interferences.

Response time (DIR input) 1 ms

Power-ON

After Power-ON the device requires a time of approx. 150 ms before valid data can be read.

Hot plugging of the encoder should be avoided.

Approvals	
UL compliant in accordance with	File no. E224618

CE compliant in accordance with

EMC Directive 2014/30/EU RoHS Directive 2011/65/EU

ATEX Directive 2014/34/EU (for Ex 2/22 variants)

¹⁾ Short circuit proof to 0 V or to output when supply voltage correctly applied.

²⁾ Over the whole temperature range.



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Terminal assignment

	Interface	Type of connection	Features	Cable (isolate unused cores individually before initial start-up)									
2 1 2 A D CET DID	CET DID	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	Ť		
	2	1, 2, A, B	SET, DIR	Core color:	WH	BN	GN	YE	GY	PK	BU	RD	shield

Interface	Type of connection	Features	M12 connector, 8-pin									
0 0.4 057 DID	CET DID	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	Ŧ	
2	3, 4	SET, DIR	Pin:	1	2	3	4	5	6	7	8	PH

+V: Supply voltage encoder +V DC

0 V: Supply voltage encoder ground GND (0 V)

C+, C-: Clock signal
D+, D-: Data signal
SET: Set input
DIR: Direction input

PH \pm : Plug connector housing (shield)

Top view of mating side, male contact base



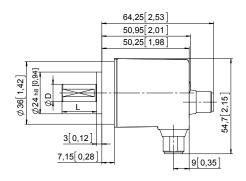
M12 connector, 8-pin

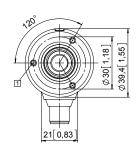
Dimensions shaft version

Dimensions in mm [inch]

Clamping flange, ø 36 [1.42] Flange type 1 and 3

1 3 x M3, 6 [0.24] deep





10 [0.39] f7 20 [0.79] 1/4" h7 12.5 [0.49]

Fit

h7

h7

12.5 [0.49]

15 [0.59]

1 4 x M3, 6 [0.24] deep

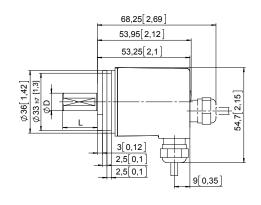
Synchro flange, ø 36 [1.42] Flange type 2 and 4

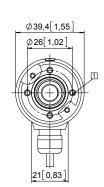
D

6 [0.24]

8 [0.32]

D	Fit	L
6 [0.24]	h7	12.5 [0.49]
8 [0.32]	h7	15 [0.59]
10 [0.39]	f7	20 [0.79]
1/4"	h7	12.5 [0.49]







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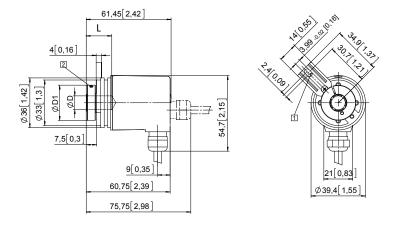
Dimensions hollow shaft version

Dimensions in mm [inch]

Flange with spring element, long Flange type 3 and 6

- Slot spring element, recommendation: torque pin DIN 7, ø 4 [0.16]
- 2 Recommended torque for the clamping ring 0.7 Nm

D	Fit	L	D1		
6 [0.24]	H7	18.5 [0.73]	24 [0.94]		
8 [0.32]	H7	18.5 [0.73]	25.5 [1.00]		
10 [0.39]	H7	18.5 [0.73]	25.5 [1.00]		
1/4" H7 18.5 [0.73] 24 [0.94]					
I = insertion denth max_blind hollow shaft					



Flange with stator coupling, ø 46 [1.81] Flange type 2 and 5

1 Recommended torque for the clamping ring 0.7 Nm

D	Fit	L	D1		
6 [0.24]	H7	18.5 [0.73]	24 [0.94]		
8 [0.32]	H7	18.5 [0.73]	25.5 [1.00]		
10 [0.39]	H7	18.5 [0.73]	25.5 [1.00]		
1/4"	H7	18.5 [0.73]	24 [0.94]		
L = insertion depth max. blind hollow shaft					

