

Absolute encoders – multiturn

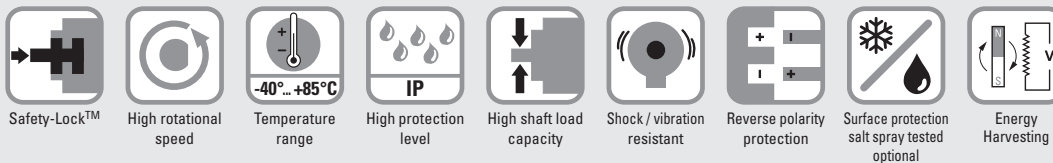
Compact electronic multiturn, magnetic

Sendix M3663 / M3683 (shaft / hollow shaft)

SSI



The Sendix M36 with Energy Harvesting Technology is an electronic multiturn encoder in miniature format, without gear and without battery. With a size of just 36 x 53 mm it offers a blind hollow shaft of up to 10 mm.



Reliable and insensitive

- Sturdy bearing construction in Safety-Lock™ design for resistance against vibration and installation errors.
- Reduced number of components ensures magnetic insensitivity.
- IP67 protection and wide temperature range -40°C ... +85°C.
- Without gear and without battery, thanks to the Energy Harvesting technology.

Application oriented

- Absolute accuracy $\pm 1^\circ$.
- Repeat accuracy $\pm 0.2^\circ$.
- Short control cycles, clock frequency with SSI up to 2 MHz.
- Max. resolution 38 bit (14 bit ST + 24 bit MT).

Order code

8.M3663 . XX2X . XXX2
Type

If for each parameter of an encoder the underlined preferred option is selected, then the delivery time will be 10 working days for a maximum of 10 pieces. Qts. up to 50 pcs. of these types generally have a delivery time of 15 working days.



a Flange

- 1 = clamping flange, IP67, \varnothing 36 mm [1.42"]
- 3 = clamping flange, IP65, \varnothing 36 mm [1.42"]
- 2 = synchro flange, IP67, \varnothing 36 mm [1.42"]
- 4 = synchro flange, IP65, \varnothing 36 mm [1.42"]

b Shaft ($\varnothing \times L$), with flat

- 1 = \varnothing 6 x 12.5 mm [0.24 x 0.49"]
- 3 = \varnothing 8 x 15 mm [0.32 x 0.59"]
- 5 = \varnothing 10 x 20 mm [0.39 x 0.79"]
- 2 = \varnothing 1/4" x 12.5 mm [0.49"]

c Interface / supply voltage

- 2 = SSI / 10 ... 30 V DC

d Type of connection

- 1 = axial cable, 1 m [3.28'] PUR
- A = axial cable, special length PUR *)
- 2 = radial cable, 1 m [3.28'] PUR
- B = radial cable, special length PUR *)
- 3 = axial M12 connector, 8-pin
- 4 = radial M12 connector, 8-pin

*) Available special lengths (connection types A, B): 2, 3, 5, 8, 10, 15 m [5.56, 9.84, 16.40, 26.25, 32.80, 49.21']
order code expansion .XXXX = length in dm
ex.: 8.M3663.432A.G322.0030 (for cable length 3 m)

e Code

- B = SSI, binary
- G = SSI, gray

f Resolution (singleturn)

- A = 10 bit ST
- 2 = 12 bit ST
- 3 = 13 bit ST
- 4 = 14 bit ST

g Resolution (multiturn)

- 2 = 12 bit MT
- 6 = 16 bit MT
- A = 20 bit MT
- 4 = 24 bit MT

Optional on request

- Ex 2/22 (only for connection types 3 and 4)
- surface protection salt spray tested

Absolute encoders – multiturn

Compact electronic multiturn, magnetic	Sendix M3663 / M3683 (shaft / hollow shaft)	SSI
Order code Hollow shaft	8.M3683 Type	.XX2X.XXX2 a b c d e f g
<p>If for each parameter of an encoder the <u>underlined preferred option</u> is selected, then the delivery time will be 10 working days for a maximum of 10 pieces. Qts. up to 50 pcs. of these types generally have a delivery time of 15 working days.</p>		10 by 10
<p>a Flange <u>2 = with stator coupling, IP65, ø 46 mm [1.81"]</u> 3 = with spring element, long, IP65 5 = with stator coupling, IP67, ø 46 mm [1.81"] 6 = with spring element, long, IP67</p> <p>b Blind hollow shaft (insertion depth max. 18.5 mm [0.73"]) 1 = ø 6 mm [0.24"] 3 = ø 8 mm [0.32"] <u>4 = ø 10 mm [0.39"]</u> 2 = ø 1/4"</p> <p>c Interface / supply voltage <u>2 = SSI / 10 ... 30 V DC</u></p>	<p>d Type of connection 1 = axial cable, 1 m [3.28'] PUR A = axial cable, special length PUR *) 2 = radial cable, 1 m [3.28'] PUR B = radial cable, special length PUR *) 3 = axial M12 connector, 8-pin <u>4 = radial M12 connector, 8-pin</u> *) Available special lengths (connection types A, B): 2, 3, 5, 8, 10, 15 m [5.56, 9.84, 16.40, 26.25, 32.80, 49.21'] order code expansion .XXXX = length in dm ex.: 8.M3683.242A.G322.0030 (for cable length 3 m)</p> <p>e Code B = SSI, binary <u>G = SSI, gray</u></p>	<p>f Resolution (singleturn) A = 10 bit ST 2 = 12 bit ST <u>3 = 13 bit ST</u> 4 = 14 bit ST</p> <p>g Resolution (multiturn) <u>2 = 12 bit MT</u> 6 = 16 bit MT A = 20 bit MT 4 = 24 bit MT</p> <p><i>Optional on request</i> - Ex 2/22 (only for connection types 3 and 4) - surface protection salt spray tested</p>

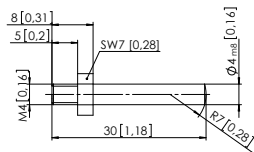
Mounting accessory for shaft encoders

Coupling	Bellows coupling ø 19 mm [0.75"] for shaft 8 mm [0.32"]	Order no. 8.0000.1102.0808
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Mounting accessory for hollow shaft encoders

Cylindrical pin, long	with fixing thread	Order no. 8.0010.4700.0000
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for flange with spring element
(flange type 3 + 6)



Connection technology

Cordset, pre-assembled	M12 female connector with coupling nut, 8-pin 2 m [6.56'] PVC cable	Order no. 05.00.6051.8211.002M
Connector, self-assembly (straight)	M12 female connector with coupling nut, 8-pin	05.CMB 8181-0

Further accessories can be found in the accessories section or in the accessories area of our website at: kuebler.com/accessories.
Additional connectors can be found in the connection technology section or in the connection technology area of our website at: kuebler.com/connection_technology.

Technical data

Mechanical characteristics	
Maximum speed	
shaft or blind hollow shaft version without shaft seal (IP65)	6000 min ⁻¹ 3000 min ⁻¹ (continuous)
shaft or blind hollow shaft version with shaft seal (IP67)	4000 min ⁻¹ 2000 min ⁻¹ (continuous)
Starting torque at 20°C [68°F]	
without shaft seal	< 0.007 Nm
with shaft seal (IP67)	< 0.01 Nm
Shaft load capacity	
radial	40 N
axial	20 N

Weight	approx. 210 g [7.41 oz]
Protection acc. to EN 60529	IP65 or IP67
Working temperature range	-40°C ... +85°C [-40°F ... +185°F]
Materials	shaft / hollow shaft: stainless steel flange: aluminum housing: zinc die-cast cable: PUR
Shock resistance acc. to EN 60068-2-27	2500 m/s ² , 6 ms
Vibration resistance acc. to EN 60068-2-6	300 m/s ² , 10 ... 2000 Hz

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Electrical characteristics	
Supply voltage	10 ... 30 V DC
Current consumption (no load)	max. 40 mA
Reverse polarity protection of the supply voltage	yes
Short-circuit proof outputs	yes ¹⁾
UL approval	file no. E224618
CE compliant acc. to	EMC guideline 2014/30/EU RoHS guideline 2011/65/EU

SSI interface	
Output driver	RS485 transceiver type
Permissible load / channel	max. +/- 30 mA
Signal level	HIGH typ 3.8 V LOW with I _{Load} = 20 mA typ 1.3 V
Resolution singleturn	10 ... 14 bit
Absolute accuracy ²⁾	±1°
Repeat accuracy	±0.2°
Number of revolutions (multiturn)	max. 24 bit
Code	binary or gray
SSI clock rate	50 kHz ... 2 MHz
Data refresh rate	2 ms
Monoflop time	≤ 15 μs
Note: If the clock cycle starts within the monoflop time a second data transfer begins with the same data. If the clock cycle starts after the monoflop time the cycle begins with the new values. The update rate is dependent on the clock speed, data length and monoflop time.	

SET input	
Input	active HIGH
Input type	comparator
Signal level (+V = supply voltage)	HIGH min. 60 % of +V, max: +V LOW max. 30 % of +V
Input current	< 0.5 mA
Min. pulse duration (SET)	10 ms
Input delay	1 ms
New position data readable after	1 ms
Internal processing time	200 ms

The encoder can be set to zero at any position by means of a HIGH signal on the SET input. Other preset values can be factory-programmed. The SET input has a signal processing time of approx. 1 ms, after which the new position data can be read via SSI. Once the SET function has been triggered, the encoder requires an internal processing time of typ. 200 ms; during this time the supply voltage must not be switched off. The SET function should be carried out whilst the encoder is at rest. The number of preset value writing cycles is limited to 10,000. If this input is not used, it should be connected to 0 V (Encoder ground GND) in order to avoid interferences.

DIR input	
Direction input: A HIGH signal switches the direction of rotation from the default cw to ccw. This inverted function can also be factory-programmed. If this input is not used, it should be connected to 0 V (Encoder ground GND) in order to avoid interferences.	
Response time (DIR input)	1 ms

Power-ON	
After Power-ON the device requires a time of approx. 150 ms before valid data can be read.	
Hot plugging of the encoder should be avoided.	

Terminal assignment

Interface	Type of connection	Features	Cable (isolate unused cores individually before initial start-up)									
			Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	⊥
2	1, 2, A, B	SET, DIR	Core color:	WH	BN	GN	YE	GY	PK	BU	RD	shield
			Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	⊥

Interface	Type of connection	Features	M12 connector, 8-pin									
			Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	⊥
2	3, 4	SET, DIR	Pin:	1	2	3	4	5	6	7	8	PH
			Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	⊥

- +V: Supply voltage encoder +V DC
- 0 V: Supply voltage encoder ground GND (0 V)
- C+, C-: Clock signal
- D+, D-: Data signal
- SET: Set input
- DIR: Direction input
- PH ⊥: Plug connector housing (shield)

Top view of mating side, male contact base



M12 connector, 8-pin

1) Short circuit proof to 0 V or to output when supply voltage correctly applied.
2) Over the whole temperature range.

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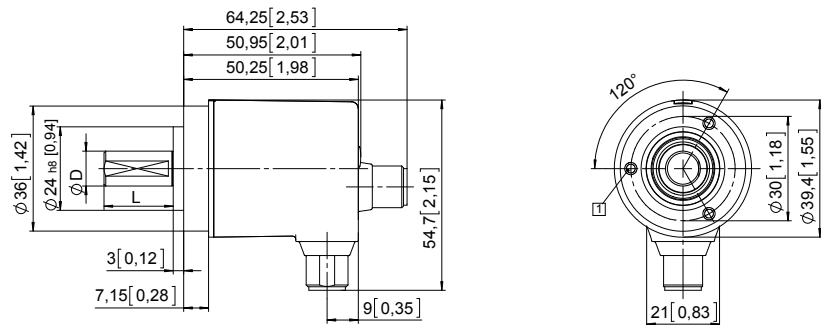
Dimensions shaft version

Dimensions in mm [inch]

Clamping flange, ø 36 [1.42]

Flange type 1 and 3

1 3 x M3, 6 [0.24] deep

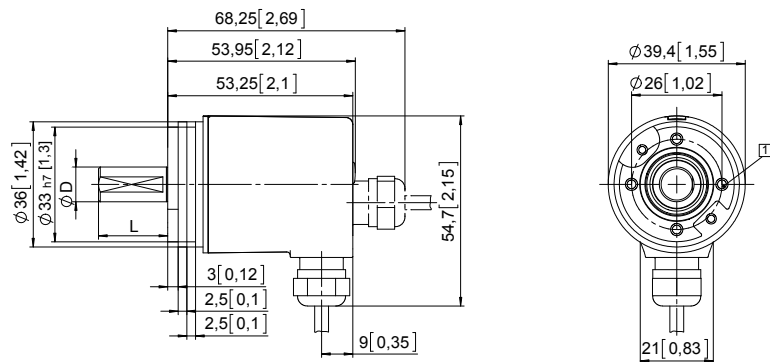


D	Fit	L
6 [0.24]	h7	12.5 [0.49]
8 [0.32]	h7	15 [0.59]
10 [0.39]	f7	20 [0.79]
1/4"	h7	12.5 [0.49]

Synchro flange, ø 36 [1.42]

Flange type 2 and 4

1 4 x M3, 6 [0.24] deep



D	Fit	L
6 [0.24]	h7	12.5 [0.49]
8 [0.32]	h7	15 [0.59]
10 [0.39]	f7	20 [0.79]
1/4"	h7	12.5 [0.49]

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Dimensions hollow shaft version

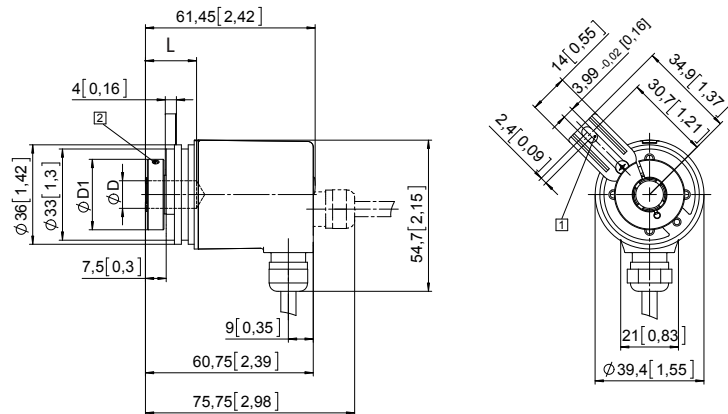
Dimensions in mm [inch]

Flange with spring element, long Flange type 3 and 6

- 1 Slot spring element, recommendation: cylindrical pin DIN 7, $\varnothing 4$ [0.16]
- 2 Recommended torque for the clamping ring 0.7 Nm

D	Fit	L	D1
6 [0.24]	H7	18.5 [0.73]	24 [0.94]
8 [0.32]	H7	18.5 [0.73]	25.5 [1.00]
10 [0.39]	H7	18.5 [0.73]	25.5 [1.00]
1/4"	H7	18.5 [0.73]	24 [0.94]

L = insertion depth max. blind hollow shaft



Flange with stator coupling, $\varnothing 46$ [1.81] Flange type 2 and 5

- 1 Recommended torque for the clamping ring 0.7 Nm

D	Fit	L	D1
6 [0.24]	H7	18.5 [0.73]	24 [0.94]
8 [0.32]	H7	18.5 [0.73]	25.5 [1.00]
10 [0.39]	H7	18.5 [0.73]	25.5 [1.00]
1/4"	H7	18.5 [0.73]	24 [0.94]

L = insertion depth max. blind hollow shaft

