

Standard optical

Sendix F5858 / F5878 (shaft / hollow shaft)

PROFINET 10





The Sendix F58 singleturn is a particularly high resolution optical encoder without gears and with 100 percent magnetic insensitivity. 19 bits total resolution, shaft up to 10 mm, blind hollow shaft up to 15 mm and certified PROFINET functionality. A minimum cycle time of 250 μs , the PROFIdrive application profile and a web server for FW updates are supported.



























Safety-Lock^{TN}

High rotational

Temperature range

Н

High protection High sh

High shaft load S

Shock / vibration resistant

Magnetic field

Reverse polarity protection

Optical sense

Latest PROFINET functionality

- PROFINET IO, RT, IRT allows integration in applications with different performance requirements.
- Supports the Isochronous Mode, can thus be implemented in networks for hard real-time requirements with clock cycles up to 250 μ s.
- Encoder profile V 4.2 with full support of various Profinet features.
- Ideal for highly synchronous applications, such as e. g. axis synchronization.
- Interoperability between many different control and drive manufacturers thanks to the PROFIdrive profile.

Reliable and insensitive

- Sturdy bearing construction in Safety-Lock™ Design for resistance against vibration and installation errors.
- Wide temperature range, -40 °C ... +80 °C.



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Order code Shaft version 8.F5858

|X|X|C|N|. **0000**

C1|2|2

a Flange

1 = clamping flange, IP65 ø 58 mm [2.28"] 3 = clamping flange, IP67 ø 58 mm [2.28"]

2 = synchro flange, IP65 ø 58 mm [2.28"]

4 = synchro flange, IP67 ø 58 mm [2.28"]

5 =square flange, IP65 \square 63.5 mm [2.5"]

7 = square flange, IP67 \square 63.5 mm [2.5"]

1 Shaft (ø x L), with flat

 $1 = 6 \times 10 \text{ mm} [0.24 \times 0.39"]$

 $2 = 10 \times 20 \text{ mm} [0.39 \times 0.79"]$

3 = 1/4" x 7/8"

4 = 3/8" x 7/8"

Interface / Supply voltage

C = PROFINET IO / 10 ... 30 V DC

Type of connection

N = 3 x axial M12 connector, 4-pin

Fieldbus profile C1 = PROFINET IO

Options - Standard types (available from 1 piece)

Surface protection salt spray tested with clamping flange IP67 and shaft ø 10 mm:

8.F5858.32CN.C122-C

V2A DIN 1.4305 AISI 303

Stainless steel V2A 1) Order expansion: 8.F5858.XXCN.C122-V2A

V4A DIN 1.4404 AISI 316L Stainless steel V4A 1) Order expansion: 8.F5858.XXCN.C122-V4A

Options – on request (for other flange/shaft combinations)

- Surface protection salt spray tested
- Stainless steel V2A
- Stainless steel V4A

XXCN. C1 2 2 0 0 0 0 0 Order code 8.F5878 . **Hollow shaft** Type

a Flange

1 = with spring element long, IP65

2 = with spring element long, IP67

3 = with stator coupling, IP65 ø 65 mm [2.56"]

4 = with stator coupling, IP67 Ø 65 mm [2.56"]

5 = with stator coupling, IP65 ø 63 mm [2.48"]

6 = with stator coupling, IP67 Ø 63 mm [2.48"]

9 = with torque stop, flexible, IP65

J = with torque stop, flexible, IP67

b Blind hollow shaft (insertion depth max. 30 mm [1.18"])

 $A = \emptyset 10 \text{ mm } [0.39"]$

 $B = \emptyset 12 \text{ mm } [0.47"]$

C = Ø 14 mm [0.55"]

D = Ø 15 mm [0.59"]

E = 0.3/8"

 $F = \emptyset 1/2$ "

Interface / Supply voltage

C = PROFINET IO / 10 ... 30 V DC

Type of connection

N = 3 x axial M12 connector, 4-pin

e Fieldbus profile C1 = PROFINET IO

Options - Standard types (available from 1 piece)

V2A DIN 1.4305 AISI 303

Stainless steel V2A 2) Order expansion:

8.F5878.2XCN.C122-V2A

V4A DIN 1.4404 AISI 316L

Stainless steel V4A 2) Order expansion: 8.F5878.2XCN.C122-V4A

Options - on request (for other flange/hollow shaft combinations)

- Surface protection salt spray tested
- Stainless steel V2A
- Stainless steel V4A

¹⁾ Only in conjunction with flange (a) = 3 or 4 and shaft (b) = 1 or 2. 2) Only in conjunction with flange (a) = 2 and hollow shaft (b) = B or D.



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|--|---|-----------------|----------------------|
| Mounting accessory for shaft | t encoders | | Order no. |
| Coupling | bellows coupling ø 19 mm [0.75"] for shaft 6 mm [0.24"] | | 8.0000.1102.0606 |
| | bellows coupling ø 19 mm [0.75"] for shaft 10 mm [0.39"] | | 8.0000.1102.1010 |
| Mounting accessory for hollo | ow shaft encoders Dimensions in mm [inch] | | Order no. |
| Torque pin, ø 4 mm for flange with spring element (flange type 1) | with fixing thread 8 [0.31] 5 [0.2] 5 [0.28] 5 | | 8.0010.4700.0000 |
| Cables and connectors | | | Order no. |
| Preassembled cables | M12 male connector with external thread, 4-pin, D coded, straight single-ended 2 m [6.56'] PUR cable | port 1 + port 2 | 05.00.6031.4411.002N |
| | M12 male connector with external thread, 4-pin, D coded, right-angle single-ended 2 m [6.56'] PUR cable | port 1 + port 2 | 05.00.6031.4511.002N |
| | M12 female connector with coupling nut, 4-pin, A coded, straight single-ended 2 m [6.56'] PUR cable | power supply | 05.00.6061.6211.002N |
| | M12 female connector with coupling nut, 4-pin, A coded, right-angle single-ended 2 m [6.56'] PUR cable | power supply | 05.00.6061.6311.002N |
| Connectors | M12 male connector with external thread, 4-pin, D coded, straight (metal) | port 1 + port 2 | 05.WASCSY4S |
| | M12 male connector with external thread, 4-pin, D coded, right-angle (metal) | port 1 + port 2 | 8.0000.5128.0000 |
| | M12 female connector with coupling nut, 4-pin, A coded, straight (plastic) | power supply | 05.B8141-0 |
| | M12 female connector with coupling nut, 4-pin, A coded, right-angle (plastic) | power supply | 05.B8241-0 |

Further Kübler accessories can be found at: kwebler.com/accessories
Further Kübler cables and connectors can be found at: kwebler.com/connection-technology



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Technical data

| Mechanical characteristics | | | |
|---|---|-------------------|--------------------------------|
| Max. speed | 9000 min ⁻¹ (short-term – 10 min) 6000 min ⁻¹ (continuous) | | |
| Starting torque at 20 °C [68 °F] | < 0.01 Nm | | |
| Moment of inertia | | | |
| shaft version blind hollow shaft version | 3.0 x 10 ⁻⁶ kg 4.0 x 10 ⁻⁶ kg | | |
| Load capacity of shaft radial axial | 80 N 40 N | | |
| Weight | Veight approx. 0.45 kg [15.87 oz] | | |
| Protection acc. to EN 60529 IP65, IP67 | | | |
| Working temperature range | -40 °C +80 °C [-40 °F +176 °F] | | +176 °F] |
| Material | Standard | | V4A DIN 1.4404 AISI 316L |
| shaft/hollow shaft flange housing | V2A aluminum aluminum | V2A V2A V2A | V4A V4A V4A |
| Shock resistance acc. EN 60068-2-27 | 27 2500 m/s², 6 ms | | |
| Vibration resistance acc. EN 60068-2-6 | resistance acc. EN 60068-2-6 100 m/s², 55 2000 Hz | | |

| Electrical characteristics | |
|--|------------|
| Power supply | 10 30 V DC |
| Current consumption (at 24 V DC) | max. 45 mA |
| Power consumption | max. 1.5 W |
| Reverse polarity protection of the power supply (V+) | yes |

| Approvals | |
|---------------------------------|------------------|
| UL compliant in accordance with | File no. E224618 |
| CE compliant in accordance with | |
| EMC Directive | 2014/30/EU |
| RoHS Directive | 2011/65/EU |
| | |

Interface characteristics PROFINET IO

| General information | | | | |
|---------------------|--|--|--|--|
| Protocol | PROFINET IO | | | |
| Classifications | RT Class 3 (IRT) Conformance Class C Application Class 6 Encoder Class 4 Netload Class III | | | |

Adjustable parameters

- Preset
- Counting direction
- Resolution per revolution MUR
- Unit speed
- IP address
- Total resolution TMR Position format
- Speed reference value
- Scaling
 - Device name
 - F-Destination Address
 - I&M 0...3 Parameter
- Alarm behavior
- Parameter write protection
- Parameter initialization

Resolution

Resolution Singleturn (MUR)

scalable 1 ... 524 288 (19 bit) default 8 192 (13 bit)

PROFINET characteristics

1&M 0 ... 3
standard telegrams (81, 82, 83, 84, 86, 88)
IRT up to 250 μs
Isochrounus Mode • MRP • LLDP

PDEVSNMPFSU

Process data

- PositionSpeed
- Failure
- Warnings



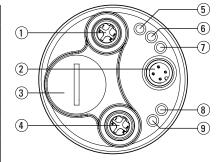
| Standard | | |
|----------|---|-------------|
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Terminal assignment bus

| Interface | Type of connection | Function | M12 connector, 4-pin | | | | | | |
|-----------|---------------------|------------|----------------------|----------------|---------------|-----------------|----------------|------------|---------|
| | | Bus Port 1 | Signal: | Transmit data+ | Receive data+ | Transmit data - | Receive data - | √ 2 | |
| | | | Abbreviation: | TxD+ | RxD+ | TxD- | RxD- | | D coded |
| | | | Pin: | 1 | 2 | 3 | 4 | (a) | |
| | | Power | Signal: | Voltage + | - | Voltage – | - | | |
| С | N | supply | Abbreviation: | + V | _ | 0 V | - | ((3 0) | |
| | (3 x M12 connector) | | Pin: | 1 | 2 | 3 | 4 | | |
| | | Bus Port 2 | Signal: | Transmit data+ | Receive data+ | Transmit data - | Receive data - | √ 2 | |
| | | | Abbreviation: | TxD+ | RxD+ | TxD- | RxD- | (0 3) | D coded |
| | | | Pin: | 1 | 2 | 3 | 4 | (a) | |

Rear side connections and display elements

| 1 | Ethernet Port – Link 2 | |
|---|------------------------|-------------------------------|
| 2 | Supply voltage | |
| 3 | Cover screw | |
| 4 | Ethernet Port – Link 1 | |
| 5 | Link 2 | flashes yellow when connected |
| 6 | BF – Bus Failture | displays network errors *) |
| 1 | SF – System Failture | displays system errors *) |
| 8 | ENC | shows status of encoder *) |
| 9 | Link 1 | flashes yellow when connected |



^{*)} see manual



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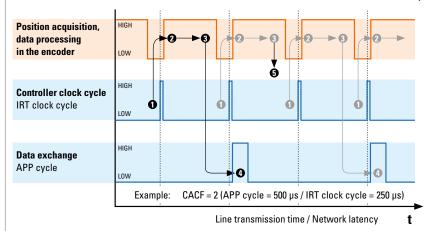
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Technology in detail

Clock synchronicity – Isochronous Real Time (IRT) in position sensor technology

In general, for time-critical applications, focus is set on very short sensor cycle times. However, in order to achieve high control performance, simply accelerating data acquisition and processing by shortest cycle times is not sufficient. All sensors and actuators are to operate according to the same clock

This is achieved thanks to a clock used for the whole network, defined by the controller. This transmit clock cycle (IRT clock) is however not necessarily the clock cycle used for process data exchange. Another cycle (application cycle) is used for this purpose, which can also be defined by the customer controller. The illustration below represents the connection between the different clock cycles.



Clock specification by controller

IRT clock cycle = Transmit clock

Data acquisition position signals Internal sensor clock synchronizes with the IRT clock. Acquisition of the sensor raw values

Data processing in the encoder
 Position data is processed and written in the buffer memory of

Data transmission via the network
 At every application cycle (APP cycle), data is read from the

buffer memory and transmitted to the controller.

All 2nd positions
Since the APP cycle is twice as long as the IRT clock cycle, every 2nd position acquired will not be transmitted.
Or: data exchange takes place only every second IRT clock cycle.

When receiving the IRT clock signal, the sensor starts reading its current measured point. This raw value is processed internally (e.g. scaling, speed calculation, etc.) and stored in a buffer memory.

The buffer memory is read at every application cycle. If it contains a value, this value is transmitted to the controller via the network.

If the application cycle is a multiple of the IRT clock cycle, it may happen that the buffered process data is not sent directly, but is overwritten, because, even though this data is acquired with every IRT clock cycle, it is sent only with every application cycle.

The ratio between application cycle and IRT clock cycle represents the CACF (Controller Application Cycle Factor).

In this example, the CACF = 2. This indicates that only every 2nd acquired position will be transmitted to the controller.

The described methodology guarantees a determinism: since the controller defines a clock cycle for the whole network, this allows ensuring that all measured values transmitted by the sensors to the controller are never older than the selected IRT cycle! Therefore, all downstream actuators can always be regulated on the basis of the latest available measured values.



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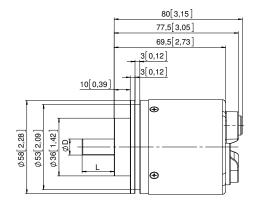
Dimensions shaft version

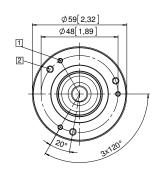
Dimensions in mm [inch]

Clamping flange, ø 58 [2.28] Flange type 1 + 3

1 3 x M3, 6 [0.24] deep

2 3 x M4, 8 [0.31] deep

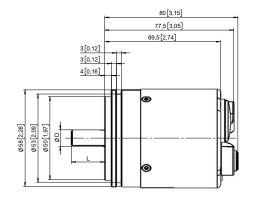


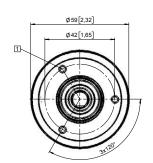


| D | Fit | L |
|-----------|-----|-----------|
| 6 [0.24] | h7 | 10 [0.39] |
| 10 [0.39] | f7 | 20 [0.79] |
| 1/4" | h7 | 7/8" |
| 3/8" | h7 | 7/8" |

Synchro flange, ø 58 [2.28] Flange type 2 + 4

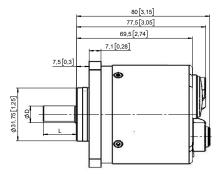
1 3 x M3, 6 [0.24] deep

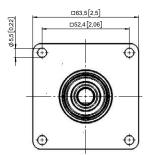




| D | Fit | L |
|-----------|-----|-----------|
| 6 [0.24] | h7 | 10 [0.39] |
| 10 [0.39] | f7 | 20 [0.79] |
| 1/4" | h7 | 7/8" |
| 3/8" | h7 | 7/8" |

Square flange, \square 63.5 [2.5] Flange type 5 + 7





| D | Fit | L |
|-----------|-----|-----------|
| 6 [0.24] | h7 | 10 [0.39] |
| 10 [0.39] | f7 | 20 [0.79] |
| 1/4" | h7 | 7/8" |
| 3/8" | h7 | 7/8" |

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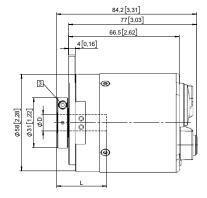
Dimensions hollow shaft version

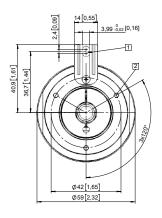
Dimensions in mm [inch]

Flange with spring element, long Flange type 1 + 2

- Slot spring element, recommendation: torque pin DIN 7, ø 4 [0.16]
- 2 3 x M3, 5.5 [0.22] deep
- 3 Recommended torque for the clamping ring 0.6 Nm

| D | Fit | L | |
|--|-----|-----------|--|
| 10 [0.39] | H7 | 30 [1.18] | |
| 12 [0.47] | H7 | 30 [1.18] | |
| 14 [0.55] | H7 | 30 [1.18] | |
| 15 [0.59] | H7 | 30 [1.18] | |
| 3/8" | H7 | 30 [1.18] | |
| 1/2" | H7 | 30 [1.18] | |
| I - insertion depth may blind hollow shaft | | | |

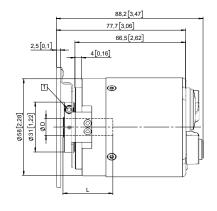


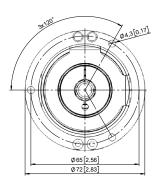


Flange with stator coupling, ø 65 [2.56] Flange type 3 + 4

Recommended torque for the clamping ring 0.6 Nm

| D | Fit | L |
|---|-----|-----------|
| 10 [0.39] | H7 | 30 [1.18] |
| 12 [0.47] | H7 | 30 [1.18] |
| 14 [0.55] | H7 | 30 [1.18] |
| 15 [0.59] | H7 | 30 [1.18] |
| 3/8" | H7 | 30 [1.18] |
| 1/2" | H7 | 30 [1.18] |
| L = insertion depth max. blind hollow shaft | | |

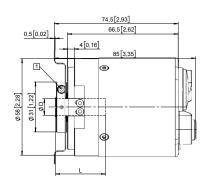


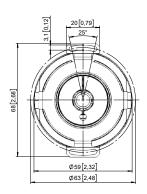


Flange with stator coupling, \emptyset 63 [2.48] Flange type 5 + 6

1 Recommended torque for the clamping ring 0.6 Nm

| D | Fit | L | |
|---|-----|-----------|--|
| 10 [0.39] | H7 | 30 [1.18] | |
| 12 [0.47] | H7 | 30 [1.18] | |
| 14 [0.55] | H7 | 30 [1.18] | |
| 15 [0.59] | H7 | 30 [1.18] | |
| 3/8" | H7 | 30 [1.18] | |
| 1/2" | H7 | 30 [1.18] | |
| L = insertion depth max. blind hollow shaft | | | |







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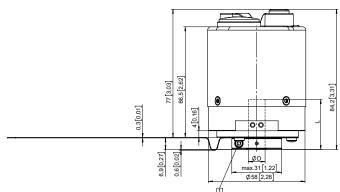
Dimensions hollow shaft version

Dimensions in mm [inch]

Flange with torque stop, flexible Flange type 9 + J

1 Recommended torque for the clamping ring 0.6 Nm

| 25[0.86] | 150 [5,91] 120.8[4,75] 76,8[3,02] 22,5[0,89] 22,5[0,89] 22,5[0,89] 22,5[0,89] 15,5[0,81] 98.8[3,89] 142,8[5,62] |
|----------|--|
| | 142,8[5,62] |
| | |



| D | Fit | L | |
|---|-----|-----------|--|
| 10 [0.39] | H7 | 30 [1.18] | |
| 12 [0.47] | H7 | 30 [1.18] | |
| 14 [0.55] | H7 | 30 [1.18] | |
| 15 [0.59] | H7 | 30 [1.18] | |
| 3/8" | H7 | 30 [1.18] | |
| 1/2" | H7 | 30 [1.18] | |
| I incoming denth many blind belleve shaft | | | |

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