

Absolute encoders – multiturn

**Compact
electronic multiturn, optical**

Sendix F3663 / F3683 (shaft / hollow shaft)

SSI / BiSS + incremental



The Sendix F36 multiturn with the patented Intelligent Scan Technology™ is an optical multiturn encoder in miniature format, without gears and with 100% insensitivity to magnetic fields.

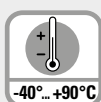
With a size of just 36 x 42 mm it offers a through hollow shaft of up to 8 mm or a blind hollow shaft of up to 10 mm.



Safety-Lock™



High rotational speed



Temperature range
-40°...+90°C



High protection level
IP



High shaft load capacity



Shock / vibration resistant



Magnetic field proof



Reverse polarity protection



SinCos



Intelligent Scan Technology™



Surface protection
salt spray-tested
optional

Reliable and insensitive

- Sturdy bearing construction in Safety-Lock™ design for resistance against vibration and installation errors.
- Reduced number of components ensures magnetic insensitivity.
- IP67 protection and wide temperature range -40 °C ... +90 °C.
- Patented Intelligent Scan Technology™ (with all singleturn and multiturn functions on one single OptoASIC) - offering highest reliability, a high resolution up to 41 bits and 100% magnetic field insensitivity.

Optimized performance

- High precision with data refresh rate of the position value ≤ 1µs.
- High resolution feedback in real-time via incremental outputs SinCos and RS422.
- Short control cycles, clock frequency with SSI up to 2 MHz / with BiSS up to 10 MHz.

Order code Shaft version

8.F3663
Type

.XXXX.XXX2
a b c d e f g

If for each parameter of an encoder the underlined preferred option is selected, then the delivery time will be 10 working days for a maximum of 10 pieces.
Qts. up to 50 pcs. of these types generally have a delivery time of 15 working days.



a Flange

- 1 = clamping flange, IP67, ø 36 mm [1.42"]
- 3 = clamping flange, IP65, ø 36 mm [1.42"]
- 2 = synchro flange, IP67, ø 36 mm [1.42"]
- 4 = synchro flange, IP65, ø 36 mm [1.42"]

b Shaft (ø x L), with flat

- 1 = ø 6 x 12.5 mm [0.24 x 0.49"]
- 3 = ø 8 x 15 mm [0.32 x 0.59"]
- 5 = ø 10 x 20 mm [0.39 x 0.79"]
- 2 = ø 1/4" x 12.5 mm [0.49"]
- 4 = ø 3/8" x 5/8"

c Interface / supply voltage

- 1 = SSI, BiSS / 5 V DC
- 2 = SSI, BiSS / 10 ... 30 V DC
- 3 = SSI, BiSS + 2048 ppr. SinCos / 5 V DC
- 4 = SSI, BiSS + 2048 ppr. SinCos / 10 ... 30 V DC
- 5 = SSI, BiSS / 5 V DC, with sensor output
- 6 = SSI, BiSS + 2048 ppr. SinCos / 5 V DC, with sensor output
- 7 = SSI, BiSS + 2048 ppr. RS422 / 5 V DC
- 8 = SSI, BiSS + 2048 ppr. RS422 / 10 ... 30 V DC

d Type of connection

- 1 = tangential cable, 1 m [3.28'] PUR
- 3 = tangential cable, 5 m [16.40'] PUR
- U = tangential cable, 10 m [32.81'] PUR
- 5 = tangential cable, 1 m [3.28'] PUR
with M12 connector for central fastening, 8-pin ¹⁾

e Code

- B = SSI, binary
- C = BiSS, binary
- G = SSI, gray

Optional on request

- surface protection salt spray tested
- other resolutions

f Resolution (singleturn)

- B = 9 bit ST
- A = 10 bit ST
- 2 = 12 bit ST
- 3 = 13 bit ST
- 4 = 14 bit ST
- 7 = 17 bit ST

g Resolution (multiturn)

- 2 = 12 bit MT
- 6 = 16 bit MT
- 4 = 24 bit MT

1) Only with interface 1 and 2.

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Order code Hollow shaft		8.F3683 Type		<div>XXXXX.XXXX2</div> <div>a b c d e f g</div>	
<div><div>a</div> Flange</div> <div>1 = with spring element, short, IP65</div> <div>3 = with spring element, long, IP65</div> <div><u>2 = with stator coupling, IP65,</u></div> <div><u>ø 46 mm [1.81"]</u></div>		<div><div>c</div> Interface / supply voltage</div> <div>1 = SSI, BiSS / 5 V DC</div> <div><u>2 = SSI, BiSS / 10 ... 30 V DC</u></div> <div>3 = SSI, BiSS + 2048 ppr. SinCos / 5 V DC</div> <div>4 = SSI, BiSS + 2048 ppr. SinCos / 10 ... 30 V DC</div> <div>5 = SSI, BiSS / 5 V DC, with sensor output</div> <div>6 = SSI, BiSS + 2048 ppr. SinCos / 5 V DC, with sensor output</div> <div>7 = SSI, BiSS + 2048 ppr. RS422 / 5 V DC</div> <div>8 = SSI, BiSS + 2048 ppr. RS422 / 10 ... 30 V DC</div>		<div><div>e</div> Code</div> <div>B = SSI, binary</div> <div>C = BiSS, binary</div> <div><u>G = SSI, gray</u></div>	
<div><div>b</div> Through hollow shaft</div> <div>1 = ø 6 mm [0.24"]</div> <div>3 = ø 8 mm [0.32"]</div> <div>2 = ø 1/4"</div> <div>Blind hollow shaft</div> <div>(insertion depth max. 14.5 mm [0.57"])</div> <div><u>4 = ø 10 mm [0.39"]</u></div>		<div><div>d</div> Type of connection</div> <div><u>1 = tangential cable, 1 m [3.28'] PUR</u></div> <div>3 = tangential cable, 5 m [16.40'] PUR</div> <div>U = tangential cable, 10 m [32.81'] PUR</div> <div>5 = tangential cable, 1 m [3.28'] PUR</div> <div>with M12 connector for central fastening, 8-pin ¹⁾</div>		<div><div>f</div> Resolution (singleturn)</div> <div>B = 9 bit ST</div> <div>A = 10 bit ST</div> <div>2 = 12 bit ST</div> <div><u>3 = 13 bit ST</u></div> <div>4 = 14 bit ST</div> <div>7 = 17 bit ST</div>	
				<div><div>g</div> Resolution (multiturn)</div> <div><u>2 = 12 bit MT</u></div> <div>6 = 16 bit MT</div> <div>4 = 24 bit MT</div>	

If for each parameter of an encoder the underlined preferred option is selected, then the delivery time will be 10 working days for a maximum of 10 pieces.

Qts. up to 50 pcs. of these types generally have a delivery time of 15 working days.

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Optional on request

- surface protection salt spray tested

- other resolutions

If for each parameter of an encoder the underlined preferred option is selected, then the delivery time will be 10 working days for a maximum of 10 pieces.
Qts. up to 50 pcs. of these types generally have a delivery time of 15 working days.



Mounting accessory for shaft encoders		Order no.
Coupling	Bellows coupling ø 19 mm [0.75"] for shaft 8 mm [0.32"]	8.0000.1102.0808
Mounting accessory for hollow shaft encoders		Order no.
Torque pin, ø 4 mm for flange with spring element (flange type 3 + 6)	with fixing thread 	8.0010.4700.0000
Cables and connectors		Order no.
Preassembled cables	M12 female connector with coupling nut, 8-pin, A coded, straight open ended 2 m [6.56'] PUR cable	05.00.6051.8211.002M
Connectors	M12 female connector with coupling nut, 8-pin, A coded, straight (metal)	05.CMB 8181-0

Further Kübler accessories can be found at: kuebler.com/accessories
Further Kübler cables and connectors can be found at: kuebler.com/connection-technology

¹⁾ Only with output circuits 1 and 2.

Absolute encoders – multiturn

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Technical data

Mechanical characteristics		
Maximum speed		
shaft version without shaft seal (IP65) or blind hollow shaft version		12000 min ⁻¹ 10000 min ⁻¹ (continuous)
shaft version with shaft seal (IP67) or hollow shaft version		10000 min ⁻¹ 8000 min ⁻¹ (continuous)
Starting torque at 20 °C [68 °F]		
	without shaft seal	< 0.007 Nm
	with shaft seal (IP67)	< 0.01 Nm
Shaft load capacity	radial	40 N
	axial	20 N
Weight		approx. 0.2 kg [7.06 oz]
Protection	housing side	IP67
acc. to EN 60529	shaft side	IP65 (solid shaft version opt. IP67)
Working temperature range		
		-40 °C ... +90 °C [-40 °F ... +194 °F]
Materials	shaft / hollow shaft	stainless steel
	flange	aluminum
	housing	zinc die-cast
	cable	PUR
Shock resistance acc. to EN 60068-2-27		2500 m/s ² , 6 ms
Vibration resistance acc. to EN 60068-2-6		100 m/s ² , 55 ... 2000 Hz

Electrical characteristics		
Supply voltage		
		5 V DC (±5 %) or 10 ... 30 V DC
Current consumption (no load)	5 V DC	max. 60 mA
	10 ... 30 V DC	max. 30 mA
Reverse polarity protection of the supply voltage		
		yes (only with 10 ... 30 V DC)
Short-circuit proof outputs		
		yes ¹⁾

SSI interface		
Output driver		
		RS485 transceiver type
Permissible load / channel		
		max. +/- 30 mA
Signal level	HIGH	typ 3.8 V
	LOW with I _{Load} = 20 mA	typ 1.3 V
Resolution singleturn		
		10 ... 17 bit
Number of revolutions (multiturn)		
		max. 24 bit
Code		
		binary or gray
SSI clock rate		
		50 kHz ... 2 MHz
Data refresh rate		
	ST resolution ≤ 14 bit	≤ 1 µs
	ST resolution ≥ 15 bit	4 µs
Monoflop time		
		≤ 15 µs
Note: If the clock cycle starts within the monoflop time a second data transfer begins with the same data. If the clock cycle starts after the monoflop time the cycle begins with the new values. The update rate is dependent on the clock speed, data length and monoflop time.		

BiSS interface		
Output driver		
		RS485 transceiver type
Permissible load / channel		
		max. +/- 30 mA
Signal level	HIGH	typ 3.8 V
	LOW with I _{Load} = 20 mA	typ 1.3 V
Resolution singleturn		
		10 ... 17 bit
Number of revolutions (multiturn)		
		max. 24 bit
Code		
		binary
BiSS Clock rate		
		50 kHz ... 10 MHz
Max. update rate		
		< 10 µs, depends on the clock rate and the data length
Data refresh rate		
	ST resolution ≤ 14 bit	≤ 1 µs
	ST resolution 17 bit	2.4 µs
Note:	- bidirectional, factory programmable parameters are: resolution, code, direction, alarms and warnings - CRC data verification	

Incremental outputs (A/B)		
	SinCos	RS422 TTL-compatible
Max. frequency -3dB	400 kHz	400 kHz
Signal level	1 V _{pp} (± 20%)	HIGH: min. 2.5 V LOW: max. 0.5 V
Short circuit proof	yes ¹⁾	yes ¹⁾
Pulse rate	2048 ppr	2048 ppr

Status output		
Output driver		
		open collector, internal pull up resistor 22 kOhm
Permissible load		
		max. 20 mA
Signal level	HIGH	+V
	LOW	< 1 V
Active		
		LOW
The status output serves to display various alarm or error messages. In normal operation the status output is HIGH (open collector with int. pull-up 22 kOhm).		
An active status output (LOW) displays: LED fault (failure or ageing) – over-temperature – undervoltage In the SSI mode, the fault indication can only be reset by switching off the supply voltage to the device.		

1) Short circuit proof to 0 V or to output when supply voltage correctly applied.

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SET input		
Input	active HIGH	
Input type	comparator	
Signal level	HIGH	min. 60 % of +V, max: +V
(+V = supply voltage)	LOW	max. 30 % of +V
Input current	< 0.5 mA	
Min. pulse duration (SET)	10 ms	
Input delay	1 ms	
New position data readable after	1 ms	
Internal processing time	200 ms	
<p>The encoder can be set to zero at any position by means of a HIGH signal on the SET input. Other preset values can be factory-programmed. The SET input has a signal processing time of approx. 1 ms, after which the new position data can be read via SSI or BiSS. Once the SET function has been triggered, the encoder requires an internal processing time of typ. 200 ms; during this time the supply voltage must not be switched off.</p> <p>The SET function should be carried out whilst the encoder is at rest.</p> <p>If this input is not used, it should be connected to 0 V (Encoder ground GND) in order to avoid interferences.</p>		

DIR input	
<p>Direction input: A HIGH signal switches the direction of rotation from the default cw to ccw. This inverted function can also be factory-programmed.</p> <p>If this input is not used, it should be connected to 0 V (Encoder ground GND) in order to avoid interferences.</p>	
Response time (DIR input)	1 ms

Power-ON		
After Power-ON the device requires a time of approx. 150 ms before valid data can be read.		
Hot plugging of the encoder should be avoided.		
Approvals		
UL compliant in accordance with	File no. E224618	
CE compliant in accordance with		
	EMC Directive	2014/30/EU
	RoHS Directive	2011/65/EU

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Terminal assignment

Interface	Type of connection	Features	Cable (isolate unused cores individually before initial start-up)										
1, 2	1, 3, U	SET, DIR, Status	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	Stat	⊥
			Core color:	WH	BN	GN	YE	GY	PK	BU	RD	VT	shield

Interface	Type of connection	Features	M12 connector, 8-pin										
1, 2	5	SET, DIR	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	⊥	
			Pin:	1	2	3	4	5	6	7	8	PH	

Interface	Type of connection	Features	Cable (isolate unused cores individually before initial start-up)													
3, 4	1, 3, U	SET, DIR, 2048 SinCos	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	A	\bar{A}	B	\bar{B}	⊥
			Core color:	WH	BN	GN	YE	GY	PK	BU	RD	BK	VT	GY-PK	RD-BU	shield

Interface	Type of connection	Features	Cable (isolate unused cores individually before initial start-up)												
5	1, 3, U	SET, DIR, Sensor output	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	0 V _{sens}	+V _{sens}	⊥	
			Core color:	WH	BN	GN	YE	GY	PK	BU	RD	VT	RD-BU	shield	

Interface	Type of connection	Features	Cable (isolate unused cores individually before initial start-up)													
6	1, 3, U	2048 SinCos, Sensor output	Signal:	0 V	+V	C+	C-	D+	D-	0 V _{sens}	+V _{sens}	A	\bar{A}	B	\bar{B}	⊥
			Core color:	WH	BN	GN	YE	GY	PK	BU	RD	BK	VT	GY-PK	RD-BU	shield

Interface	Type of connection	Features	Cable (isolate unused cores individually before initial start-up)												
7, 8	1, 3, U	2048 incr. RS422	Signal:	0 V	+V	C+	C-	D+	D-	A	\bar{A}	B	\bar{B}	⊥	
			Core color:	WH	BN	GN	YE	GY	PK	BK	VT	GY-PK	RD-BU	shield	

+V: Supply voltage encoder +V DC
 0 V: Supply voltage encoder ground GND (0 V)
 0 V_{sens} / +V_{sens}: Using the sensor outputs of the encoder, the voltage present can be measured and if necessary increased accordingly.
 C+, C-: Clock signal
 D+, D-: Data signal
 A, \bar{A} : Incremental output channel A (cosine)
 B, \bar{B} : Incremental output channel B (sine)
 SET: Set input
 DIR: Direction input
 Stat: Status output
 PH ⊥: Plug connector housing (shield)

Top view of mating side, male contact base



M12 connector, 8-pin

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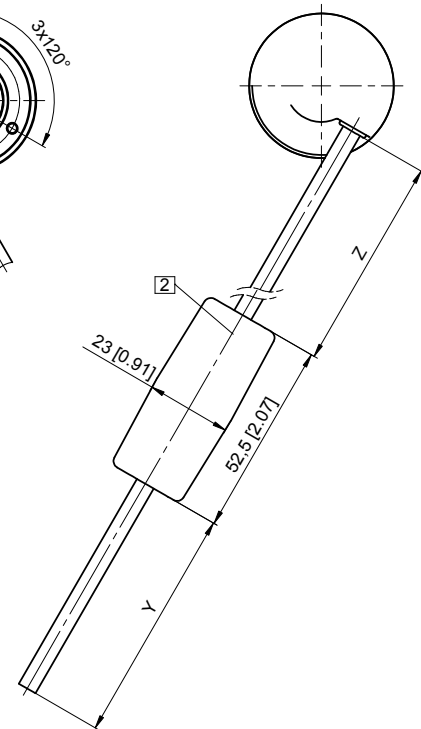
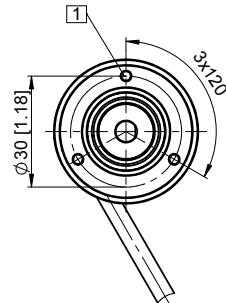
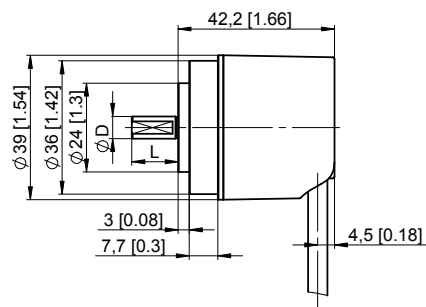
SSI / BiSS

Dimensions shaft version

Dimensions in mm [inch]

Clamping flange, $\varnothing 36$ [1.42] Flange type 1 and 3

- 1 3 x M3, 6 [0.24] deep
- 2 Battery (in the cable)

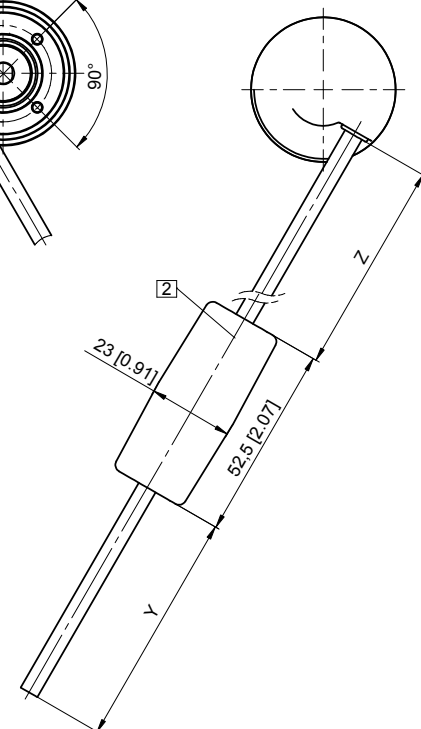
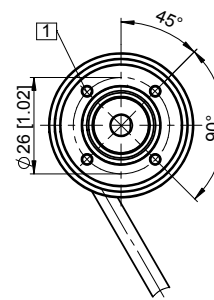
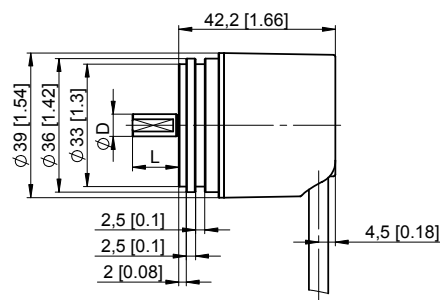


D	Fit	L
6 [0.24]	h7	12.5 [0.49]
8 [0.32]	h7	15 [0.59]
10 [0.39]	f7	20 [0.79]
1/4"	h7	12.5 [0.49]
3/8"	h7	5/8"

Y	Z
1 m [3.28']	0.15 m [0.49']
5 m [16.40']	0.15 m [0.49']

Synchro flange, $\varnothing 36$ [1.42] Flange type 2 and 4 (drawing with cable)

- 1 4 x M3, 6 [0.24] deep
- 2 Battery (in the cable)



D	Fit	L
6 [0.24]	h7	12.5 [0.49]
8 [0.32]	h7	15 [0.59]
10 [0.39]	f7	20 [0.79]
1/4"	h7	12.5 [0.49]
3/8"	h7	5/8"

Y	Z
1 m [3.28']	0.15 m [0.49']
5 m [16.40']	0.15 m [0.49']

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Dimensions hollow shaft version

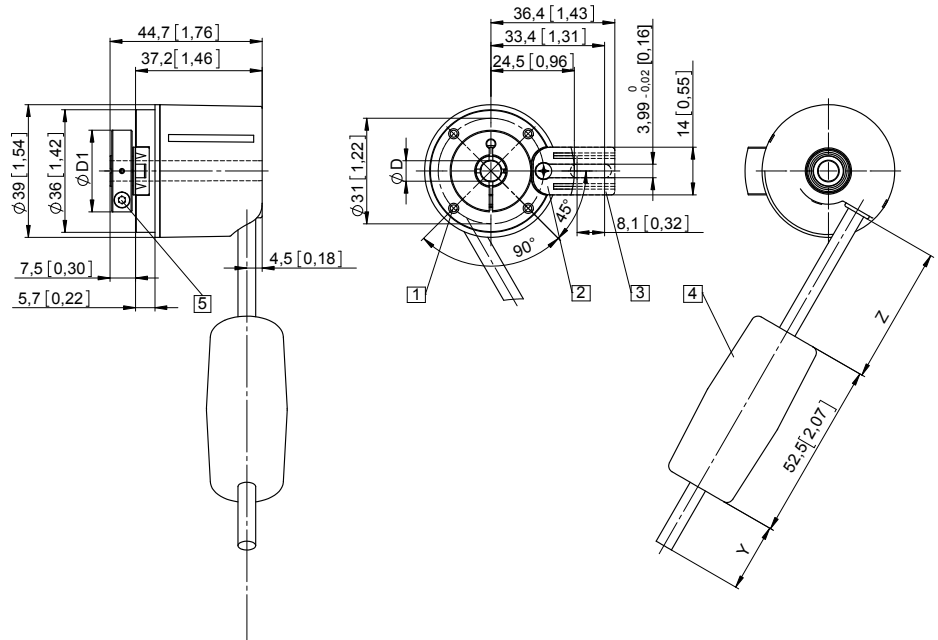
Dimensions in mm [inch]

Flange with spring element

Flange type 1 and 3

(drawing with spring element short,
spring element long is shown dashed)

- 1 4 x M2.5, 5 [0.20] deep
- 2 Spring element, short
recommendation:
torque pin DIN 7, σ 4 [0.16]
- 3 Spring element, long
recommendation:
torque pin DIN 7, σ 4 [0.16]
- 4 Battery (in the cable)
- 5 Recommended torque for the
clamping ring 0.6 Nm



D	Fit	D1
6 [0.24]	H7	24 [0.94]
8 [0.32]	H7	25.5 [1.00]
10 [0.39] *)	H7	25.5 [1.00]
1/4"	H7	24 [0.94]

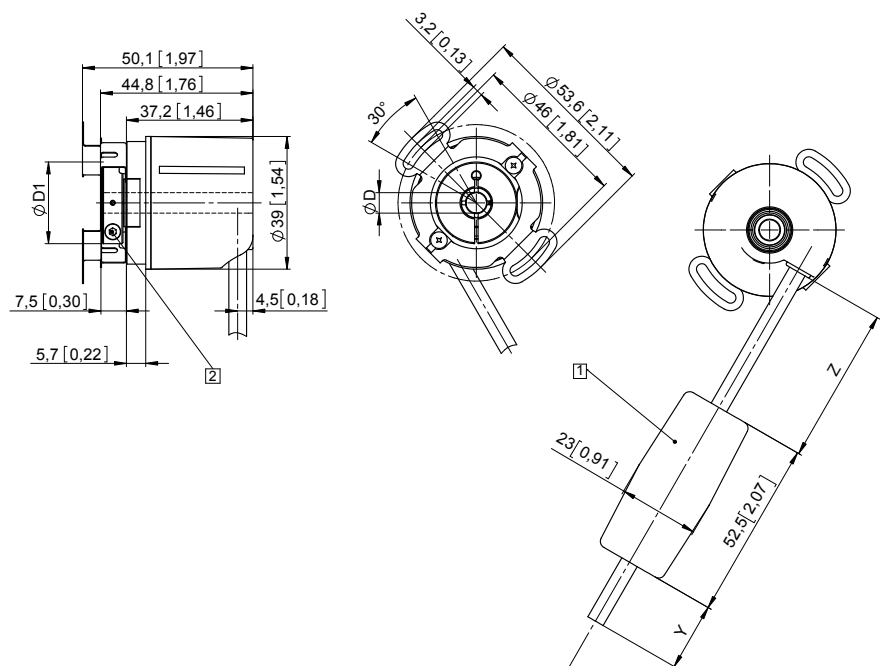
*) Blind hollow shaft,
insertion depth max. = 14.5 mm [0.57"]

Y	Z
1 m [3.28']	0.15 m [0.49']
5 m [16.40']	0.15 m [0.49']

Flange with stator coupling, ø 46 [1.81]

Flange type 2

- 1 Battery (in the cable)
- 2 Recommended torque for the clamping ring 0.6 Nm



D	Fit	D1
6 [0.24]	H7	24 [0.94]
8 [0.32]	H7	25.5 [1.00]
10 [0.39] *)	H7	25.5 [1.00]
1/4"	H7	24 [0.94]

*) Blind hollow shaft,
insertion depth max. = 14.5 mm [0.57"]

Y	Z
1 m [3.28']	0.15 m [0.49']
5 m [16.40']	0.15 m [0.49']