

Absolute encoders - singleturn

Standard optical	Sendix 5858 / 5878 (shaft / hollow shaft)	EtherCAT
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The singleturn encoders 5858 and 5878 with second-generation EtherCAT interface and optical sensor technology are ideal for use in all applications with an EtherCAT interface.

The data communication is based on CAN over EtherNet and ideally suited for use in real time applications.

These encoders are available with a solid shaft up to a maximum of 10 mm or a blind hollow shaft up to 15 mm.



EtherCAT
Conformance tested



Safety-Lock™



High rotational speed



Temperature range
-40...+80°C



High protection level
IP



High shaft load capacity



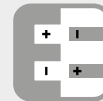
Shock / vibration resistant



Magnetic field proof



Short-circuit proof



Reverse polarity protection



Optical sensor



Surface protection salt spray-tested optional

Reliable

- EtherCAT conformance tested.
- Integration of the latest slave – EtherCAT stack from Beckhoff, version 5.01.
- Ideally suited for use in harsh outdoor environments, thanks to IP67 protection and rugged housing construction.

Flexible

- Use of CoE (CAN over EtherNet).
- Genuine new position information as a result of minimal cycle time of 62.5 µs in the DC mode.
- Faster, easier error-free connection thanks to M12 connectors.
- Supports Hot-Connect.

Order code

Shaft version

8.5858

Type

. XXB2 . B2 12

a Flange

- 1** = clamping flange, IP65 ø 58 mm [2.28"]
- 3 = clamping flange, IP67 ø 58 mm [2.28"]
- 2** = synchro flange, IP65 ø 58 mm [2.28"]
- 4 = synchro flange, IP67 ø 58 mm [2.28"]
- 5 = square flange, IP65 □ 63.5 mm [2.5"]
- 7 = square flange, IP67 □ 63.5 mm [2.5"]

b Shaft (ø x L), with flat

- 1** = 6 x 10 mm [0.24 x 0.39"]¹⁾
- 2** = 10 x 20 mm [0.39 x 0.79"]²⁾
- 3 = 1/4" x 7/8"
- 4 = 3/8" x 7/8"

c Interface / supply voltage

B = EtherCAT / 10 ... 30 V DC

d Type of connection

removable bus terminal cover
2 = 3 x M12 connector, 4-pin

e Fieldbus profile

B2 = EtherCAT with CoE (CAN over EtherNet)

Optional on request
- Ex 2/22
- surface protection salt spray tested

Order code

Hollow shaft

8.5878

Type

. XXB2 . B2 12

a Flange

- 1 = with spring element, long, IP65
- 2 = with spring element, long, IP67
- 3 = with stator coupling, IP65 ø 65 mm [2.56"]
- 4 = with stator coupling, IP67 ø 65 mm [2.56"]
- 5** = with stator coupling, IP65 ø 63 mm [2.48"]
- 6 = with stator coupling, IP67 ø 63 mm [2.48"]

b Blind hollow shaft

- (insertion depth max. 30 mm [1.18"])
- 3 = ø 10 mm [0.39"]
- 4** = ø 12 mm [0.47"]
- 5 = ø 14 mm [0.55"]
- 6 = ø 15 mm [0.59"]
- 8 = ø 3/8"
- 9 = ø 1/2"

c Interface / supply voltage

B = EtherCAT / 10 ... 30 V DC

d Type of connection

removable bus terminal cover
2 = 3 x M12 connector, 4-pin

e Fieldbus profile

B2 = EtherCAT with CoE (CAN over EtherNet)

Optional on request
- Ex 2/22
- surface protection salt spray tested

1) Preferred type only in conjunction with flange type 2.
2) Preferred type only in conjunction with flange type 1.

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Mounting accessory for shaft encoders		Order no.
Coupling	bellows coupling ø 19 mm [0.75"] for shaft 6 mm [0.24"]	8.0000.1102.0606
	bellows coupling ø 19 mm [0.75"] for shaft 10 mm [0.39"]	8.0000.1102.1010

Mounting accessory for hollow shaft encoders		Order no.
Torque pin, ø 4 mm for flange with spring element (flange type 1 + 2)	with fixing thread 	8.0010.4700.0000

Cables and connectors			Order no.
Preassembled cables	M12 male connector with external thread, 4-pin, D coded, straight single-ended 2 m [6.56'] PUR cable	Bus IN + Bus OUT	05.00.6031.4411.002M
	M12 female connector with coupling nut, 4-pin, A coded, straight single-ended 2 m [6.56'] PUR cable	supply voltage	05.00.6061.6211.002M
Connectors	M12 male connector with external thread, 4-pin, D coded, straight (metal)	Bus IN + Bus OUT	05.WASCSY4S
	M12 female connector with coupling nut, 4-pin, A coded, straight (plastic)	supply voltage	05.B8141-0

Further Kübler accessories can be found at: kuebler.com/accessories
 Further Kübler cables and connectors can be found at: kuebler.com/connection-technology

Technical data

Mechanical characteristics		
Maximum speed	IP65 up to 70 °C [158 °F]	9000 min ⁻¹ , 7000 min ⁻¹ (continuous)
	IP65 up to T _{max}	7000 min ⁻¹ , 4000 min ⁻¹ (continuous)
	IP67 up to 70 °C [158 °F]	8000 min ⁻¹ , 6000 min ⁻¹ (continuous)
	IP67 up to T _{max}	6000 min ⁻¹ , 3000 min ⁻¹ (continuous)
Starting torque - at 20 °C [68 °F]	IP65	< 0.01 Nm
	IP67	< 0.05 Nm
Mass moment of inertia	shaft version	3.0 x 10 ⁻⁶ kgm ²
	hollow shaft version	6.9 x 10 ⁻⁶ kgm ²
Load capacity of shaft	radial	80 N
	axial	40 N
Weight		approx. 0.50 kg [17.64 oz]
Protection acc. to EN 60529	housing side	IP67
	shaft side	IP65, opt. IP67
Working temperature range		-40 °C ... +80 °C [-40 °F ... +176 °F]
Material	shaft/hollow shaft	stainless steel
	flange	aluminum
	housing	zinc die-cast
Shock resistance acc. to EN 60068-2-27		2500 m/s ² , 6 ms
Vibration resistance acc. to EN 60068-2-6		100 m/s ² , 55 ... 2000 Hz

Electrical characteristics	
Supply voltage	10 ... 30 V DC
Power consumption (no load)	max. 110 mA
Reverse polarity protection of the supply voltage	yes

Interface characteristics EtherCAT	
Resolution	1 ... 65535 (16 bit), scalable default: 8192 (13 bit)
Protocol	EtherNet / EtherCAT

Approvals		
UL compliant in accordance with	File no. E224618	
CE compliant in accordance with	EMC Directive	2014/30/EU
	RoHS Directive	2011/65/EU
	ATEX Directive	2014/34/EU (for Ex 2/22 variants)

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Diagnostic LED (red) LED is ON with the following fault conditions: Sensor error (internal code or LED error), low voltage, over-temperature		2 x Link LEDs (yellow) LED is ON with the following conditions (port IN and port OUT): Link detected
Run LED (green) LED is ON with the following conditions: Preop-, Safeop and Op-State (EtherCAT status machine)		Modes Freerun, Distributed Clock

General information about CoE (CAN over EtherNet)

The EtherCAT encoders support the CANopen communication profile according to DS301. In addition device-specific profiles like the encoder profile DS406 are available.

Scaling, preset values, limit switch values and many other parameters can be programmed via the EtherCAT bus.

When switching the device on, all parameters are loaded from an EEPROM, where they were saved previously to protect them against power-failure.

The following output values may be combined as PDO (PDO mapping): **position, speed, temperature values** and **working area state** as well as other process values.

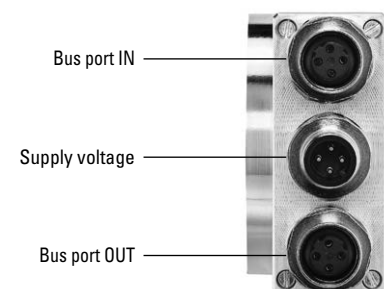
CANopen encoder profile 3.2.10 CoE (CAN over EtherNet)

The following parameters are programmable:

- Position update time of 62.5 μ s.
- EtherCAT certificate of conformity.
- Speed with sign.
- Four units for speed calculation: steps/sec, steps/100 ms, steps/10 ms, rotation/min.
- Time stamp as system time at the point in time when the position is read out.
- Two working area state registers.
- Along with the scaled position, the raw data – position as process value – is also mappable.
- Dynamic mapping.
- Gating time: setting of the time interval, via which the speed value can be interpolated.
- Sensor temperature in degrees Celsius.
- Comprehensive plausibility test when downloading parameters to the encoder.
- Alarm and warning messages.
- User interface with visual display of bus and fault status – 4 LEDs.
- Extended error management for position sensing with integrated temperature control.
- Implementation of the latest CANopen profile 3.2.10 from the 18th February 2011.
- Hot-Connect – Support for rapid change of Bus-topology.

Terminal assignment bus

Interface	Type of connection	Function	M12 connector, 4-pin					
			Signal:	Transmit data+	Receive data+	Transmit data -	Receive data -	
B	2 (3 x M12 connector)	Bus port IN	Signal:	Transmit data+	Receive data+	Transmit data -	Receive data -	D coded
			Abbreviation:	TxD+	RxD+	TxD-	RxD-	
			Pin:	1	2	3	4	
		Power supply	Signal:	Voltage +	–	Voltage –	–	
			Abbreviation:	+ V	–	0 V	–	
			Pin:	1	2	3	4	
		Bus port OUT	Signal:	Transmit data+	Receive data+	Transmit data -	Receive data -	D coded
			Abbreviation:	TxD+	RxD+	TxD-	RxD-	
			Pin:	1	2	3	4	



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Dimensions shaft version, with removable bus terminal cover

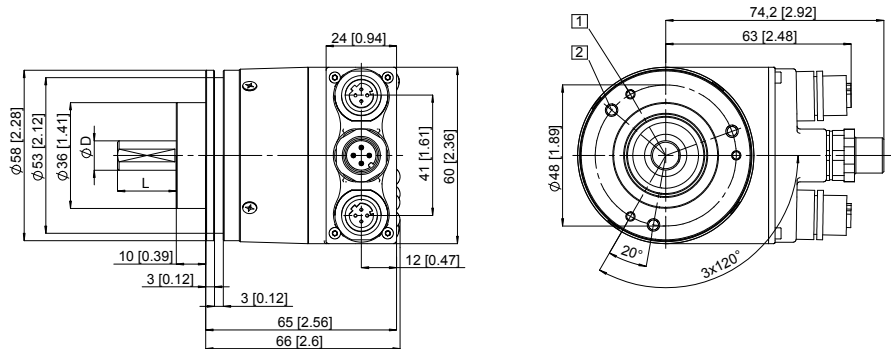
Dimensions in mm [inch]

Clamping flange, ø 58 [2.28]

Flange type 1 and 3

- 1 3 x M3, 6 [0.24] deep
- 2 3 x M4, 8 [0.32] deep

D	Fit	L
6 [0.24]	h7	10 [0.39]
10 [0.39]	f7	20 [0.79]
1/4"	h8	7/8"
3/8"	h8	7/8"

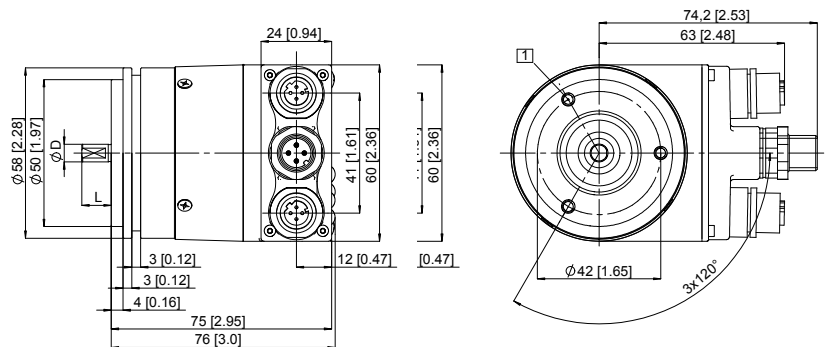


Synchro flange, ø 58 [2.28]

Flange type 2 and 4

- 1 3 x M4, 6 [0.24] deep

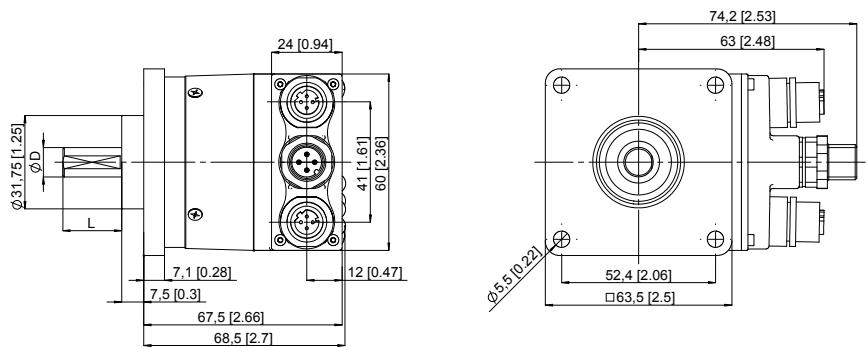
D	Fit	L
6 [0.24]	h7	10 [0.39]
10 [0.39]	f7	20 [0.79]
1/4"	h8	7/8"
3/8"	h8	7/8"



Square flange, □ 63.5 [2.5]

Flange type 5 and 7

D	Fit	L
6 [0.24]	h7	10 [0.39]
10 [0.39]	f7	20 [0.79]
1/4"	h8	7/8"
3/8"	h8	7/8"



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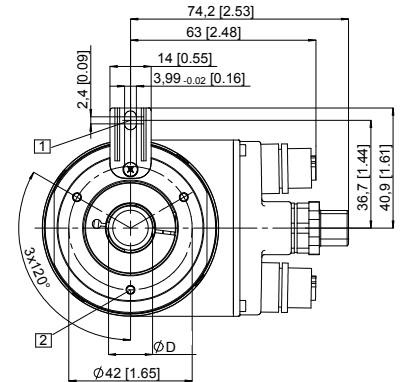
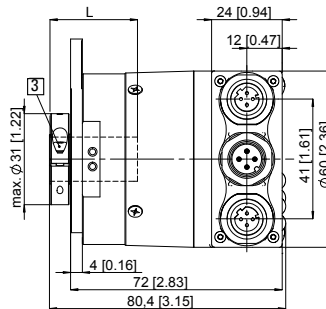
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Dimensions hollow shaft version (blind hollow shaft), with removable bus terminal cover

Dimensions in mm [inch]

Flange with spring element, long Flange type 1 and 2

- 1 Slot spring element, recommendation: torque pin DIN 7, \varnothing 4 [0.16]
- 2 3 x M3, 5.5 [0.22] deep
- 3 Recommended torque for the clamping ring 0.6 Nm

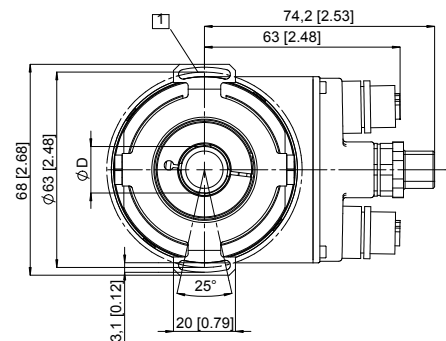
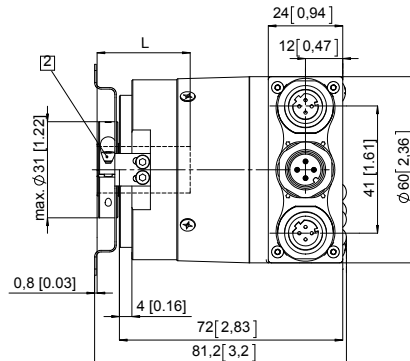


D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]

L = insertion depth max. blind hollow shaft

Flange with stator coupling, \varnothing 63 [2.48] Flange type 5 and 6

- 1 Fixing screws DIN 912 M3 x 8 (washer included in delivery)
- 2 Recommended torque for the clamping ring 0.6 Nm

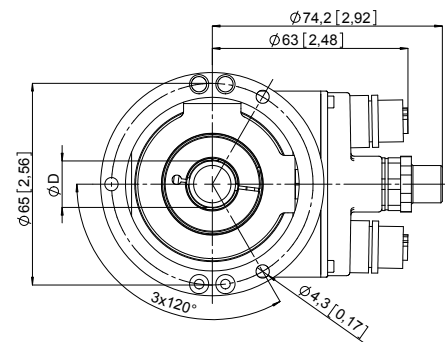
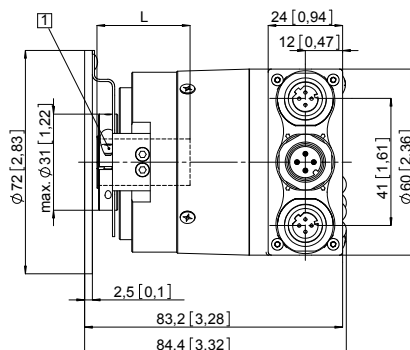


D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]

L = insertion depth max. blind hollow shaft

Flange with stator coupling, \varnothing 65 [2.56] Flange type 3 and 4

- 1 Recommended torque for the clamping ring 0.6 Nm



D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]

L = insertion depth max. blind hollow shaft